

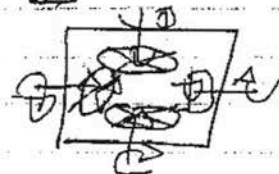
# Turbulence Theory

192.

## An Introduction

P. Diamond  
i.e.

I.) Basics of Fluid Turbulence (30)



Characteristics of Fluid Turbulence:

"turbulent" vs "noise" → energy flux

- broad range of spatio-temporal scales excited  
Ref. U. Frisch
- decay of large scale energy → need input/stirring to maintain stationarity - "The legacy of A. N. Kolmogorov"
- energy input dissipated as heat (to maintain stationarity) → viscosity  
→ irreversibility
- irreversible mixing occurs → i.e. passive tracer
- intermittency manifested  
i.e. spatial → coherent structures (i.e. vortices)  
temporal → bursts probe trace
- self-similarity/scale-similarity:  
turbulence looks the same on all scales, except the very largest (stirring) and the very smallest (dissipation)  
Caveat: Intermittency - memory of large scales on small.

(c) Navier Stokes Equation - Describes Fluid

$$\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\frac{\nabla p}{\rho} + \nu \nabla^2 \underline{v}$$

$\frac{\partial \underline{v}}{\partial t}$  → advection/straining → nonlinearity  
 $\frac{\nabla p}{\rho}$  → pressure  
 $\nu \nabla^2 \underline{v}$  → viscous diffusion of momentum

$\rho = 1$   
hereafter

$$\nabla \cdot \underline{v} = 0 \quad \text{incompressibility}$$

Note: Pressure determined from incompressibility

c.e.

$$\nabla \cdot \left[ \frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right] = -\nabla^2 p + \nu \nabla^2 (\nabla \cdot \underline{v})$$

$$\nabla^2 p = -\nabla \cdot \left[ \frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right]$$

$$p = -\nabla^{-2} \left[ \nabla \cdot \left( \frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right) \right]$$

$$= -\frac{1}{4\pi D} \int \frac{d^3 x' \nabla_i \cdot \left[ \frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right]_i}{|\underline{x} - \underline{x}'|}$$

More generally, can eliminate  $p$

$$\partial_t v_i + (\partial_{ij} - \partial_{ij} \nabla^{-2}) \partial_j (v_j v_k) = \nu \nabla^2 v_i$$

Key Parameter: Reynolds #

$$Re = \frac{|\underline{v} \cdot \nabla \underline{v}|}{|\nu \nabla^2 \underline{v}|}$$

$$\sim \frac{V(L) L}{\nu}$$

$\sim$  nonlinearity  
collisional diffusion  
measure of strength  
of NL.

-  $Re$  usually referenced to largest scale

$$L = L_{max}$$

$$V(L) = \text{large scale velocity}$$

-  $Re$  always referenced to a particular scale

$$L_{max}, \lambda = \left[ \frac{\langle (\partial_i v_j)^2 \rangle}{\langle v_i^2 \rangle} \right]^{-1/2}, \quad \lambda_{dissip.}, (Re=1)$$

(Taylor Scale)

-  $Re \gg 1$  in turbulent { pipe flow  
atmosphere  
etc

$$Re \sim 10^6 - 10^8, \text{ etc.}$$

i.e. planetary boundary layer:  $h_{out} \sim 1 \text{ km}$   
 $\sim 10^5 \text{ cm}$   
 $h_{diss} \sim 1 \text{ cm}$

$\Rightarrow$  6 decades

-  $Re$ : measure of ratio of inertial mixing of momentum to collisional mixing.

(4)

## ii) Experimental 'Laws' of Fully Developed Turbulence

► Much / most of turbulence theory is empirically motivated. Experimental info / results preceded sophisticated theoretical analyses....

The experimental facts:

### 1.) 2/3 Law (Mandane)

In a turbulent flow with  $Re \gg 1$ ,  
 $\langle \delta v(l)^2 \rangle$  (mean square velocity increment  
 between two scales) separated by distance  
 $l$ ) scales as  $l^{2/3}$ .

i.e.

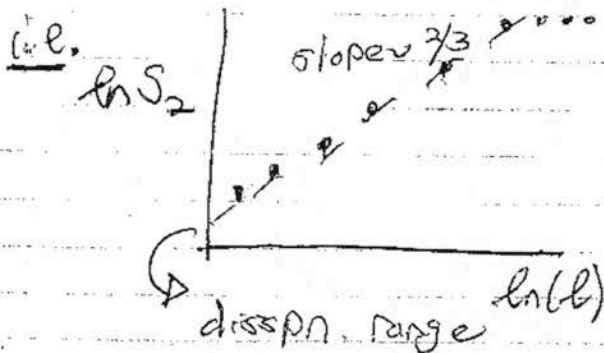
$$\delta v(l) = |v(x+l) - v(x)|$$

⇒ {a difference!}

$$S_2(l) = \langle \delta v(l)^2 \rangle \sim l^{2/3}$$

→ Fundamental scaling relation

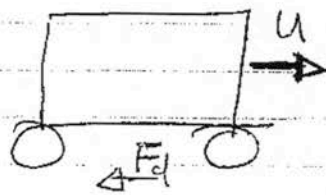
2<sup>nd</sup> order structure function



## B) Law of Finite Energy Dissipation (Profound)

If, in an experiment on turbulent flow, all the control parameters are kept the same, except the viscosity, which is lowered as much as possible, the energy dissipation per unit mass  $dE/dt$  behaves in a way consistent with a finite limit.

- What means 'Energy Dissipation Rate'?



Consider a car experiencing atmospheric drag

$$F_d = \frac{1}{2} C_D \rho S U^2$$

↓  
face surface area

c.e.  $\left| \frac{\Delta p}{\Delta t} \right|$

$$p = \rho S (U^2) U$$

→ momentum in air of slug:

$$M = \rho S U^2 \rightarrow \text{mass}$$

if assume air momentum  $V=U$   
completely transferred to car

$$\frac{dp}{dt}_{\text{car}} = F_d = \rho S U^2$$

$\frac{C_D}{2}(Re) \equiv$  drag coefficient (slowly varying function of  $Re$ , depends on shape, etc.)

$$\therefore \bar{F}_d = \frac{C_D}{2} \rho S U^2$$

Now, power dissipated by drag force

$$P_d = \bar{F}_d U$$

$$\Rightarrow \rho_d = \frac{C_D}{2} \rho S U^3$$

Energy dissipation rate (per volume)  $E = P_d / \text{Mass}$

$$= \frac{C_D}{2} \frac{U^3}{L}$$

also NS  $\Rightarrow \partial_t \langle v^2 \rangle \sim - \langle \underline{v} \cdot \nabla v^2 \rangle \sim U^3/L$

$\rightarrow$  Why should we care?

Note, energy budget:

$$\frac{\partial v_i}{\partial t} + v_j \partial_j v_i - \nu \nabla^2 v_i = -\partial_i p$$

$$\partial_t \frac{V_i^2}{2} + \partial_j \frac{V_j V_i^2}{2} - \nu V_i \partial^2 V_i = -V_i \partial_i p$$

$\langle \rangle \equiv$  ensemble (fast space-time avg.)

$$\partial_t \left\langle \frac{V_i^2}{2} \right\rangle + \left\langle \partial_j \frac{V_j V_i^2}{2} \right\rangle - \nu \langle V_i \partial^2 V_i \rangle$$

surface terms  $= \langle \partial_i V_i p \rangle$   
upon IBP

$$\Rightarrow \partial_t \left\langle \frac{V_i^2}{2} \right\rangle = -\nu \langle |\partial V|^2 \rangle$$

but  $\epsilon = -\partial_t \left\langle \frac{V_i^2}{2} \right\rangle$  ! (- dissipation rate)

$$\epsilon = \nu \langle |\partial V|^2 \rangle$$

$\rightarrow$  experiments suggest that  $\epsilon \rightarrow$  finite as  $\nu \rightarrow 0$  ! ! !  $\leftrightarrow$  pre-markable

$\rightarrow$  suggests that extremely large  $\partial V$  forms as  $\nu \rightarrow 0$ , singular vortex sheets

$\Rightarrow$  singular velocity gradients formed in limit of weak viscosity ! !

Heart of turbulence problem is grappling with singularity (especially its degree) of velocity gradients.



No. B. : { Dissipation Law  
Singularity formation is at the heart of why turbulence is a "hard" problem.

Re: Dissipation Law:

$$\epsilon \sim \frac{U^3}{L} \sim U^2 / (L/U)$$

$$\sim \frac{\text{K.E. per Mass}}{\text{circulation Time}}$$

i.e.  $\rightarrow$  in 1 macro circulation time, a finite fraction of (macro) kinetic energy is dissipated by viscosity.

$\rightarrow$  dissipation time scale is  $(L/U)$ .

V. Kalmogorov's Hypotheses and their Predictions / Implications.  $\rightarrow$  K41 Theory of Turbulence

1.1: In the limit of  $Re \rightarrow \infty$ , all possible symmetries of the Navier-Stokes equation, usually broken by the mechanisms producing the turbulent flow, are restored in a statistical sense at small scales and away from boundaries.

lose memory



What means?

- "small scales":  $l \ll l_0$

integral scale  $\rightarrow$  characteristic of production.

- symmetries

First, symmetries of Navier-Stokes Eqn.!

a.) space translations  $\Omega \rightarrow \Omega + \mathcal{D}$   
(no explicit  $\Omega$  dep.)

b.) time translation  $t \rightarrow t + \mathcal{T}$   
(no  $t$  dep.)

\* c.) Galilean boosts  $\begin{cases} \Omega \rightarrow \Omega + \underline{U}t \\ \underline{V} \rightarrow \underline{V} + \underline{U} \end{cases} \quad \underline{V} = \underline{u} + \underline{V}(\Omega - \underline{u}t)$   
(no frame dep.)

i.e.  $\frac{\partial \underline{V}}{\partial t} + \underline{V} \cdot \nabla \underline{V} = -\nabla \mathcal{P} + \nu \nabla^2 \underline{V}$

insert  $\Rightarrow$

$$= \underline{u} \cdot \nabla \underline{V} + \underline{u} \cdot \nabla \underline{V} + \frac{\partial \underline{V}}{\partial t} + \underline{V} \cdot \nabla \underline{V} = -\nabla \mathcal{P} + \nu \nabla^2 \underline{V}$$

d.) Parity (left-right)  $\underline{x} \rightarrow -\underline{x}, \underline{V} \rightarrow -\underline{V}$   
(no preferred direction)

e.) Rotation (no preferred direction)  $\begin{cases} \Omega \rightarrow R \Omega \\ \underline{V} \rightarrow R \underline{V} \end{cases}$

\* e.) Scaling (for  $\nu \rightarrow 0$ )  $\Rightarrow$  critical: scale elimination; hand passing

$$\Gamma, \underline{v}, t \rightarrow \lambda \Gamma, \lambda^a \underline{v}, \lambda^b t$$

i.e.  $\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\nabla p$

$$\begin{aligned} \underline{v} &\rightarrow \lambda^a \underline{v} \\ t &\rightarrow \lambda^b t \end{aligned}$$

$$\frac{\lambda^a \partial \underline{v}}{\lambda^b \partial t} + \frac{\lambda^{2a}}{\lambda} \underline{v} \cdot \nabla \underline{v} = -\nabla p$$

$\hookrightarrow$  From  $\nabla \cdot \underline{v} = 0$

$$\lambda^{2a-1} = \lambda^{a-b}$$

$$b = 1 - a$$

$$\Rightarrow \lambda^{-(a-1)} = \lambda^b$$

$\therefore$  scalings  $\Gamma \rightarrow \lambda \Gamma, \underline{v} \rightarrow \lambda^a \underline{v}, t \rightarrow \lambda^b t$

Now, turbulence onset  $\Rightarrow$  symmetry breaking!

i.e. ① KH: shear breaks  $\left\{ \begin{array}{l} \text{translational} \\ \text{rotational} \end{array} \right.$  invariance

②



rigid body boundary flow, etc

③ Flushing toilet  $\left\{ \begin{array}{l} \text{space} \\ \text{time} \end{array} \right.$

etc.

\* However, fully developed turbulence tends to restore symmetry, except near boundaries, on small scale.

b.c.  $\leftrightarrow$  boundary conditions

i.e. if  $\delta v(r, l) = v(r+l) - v(r)$   
 $\Rightarrow$

$$\delta v(r+l) = \delta v(r)$$

similarly: isotropy, parity ...

(facilitates scaling approach)

H2 For  $Re \rightarrow \infty$  turbulence, at small scales and away from boundaries, the flow is self-similar at small scales

i.e. possesses a unique scaling exponent  $h$  s/t

$$\delta v(r, \lambda l) \rightarrow \lambda^h \delta v(r, l)$$

(addresses 2/3 Law)

H3 With assumptions similar to H1, the turbulent flow has a finite, nonvanishing mean rate of dissipation  $\epsilon$  per unit mass.

$Re \rightarrow \infty \Rightarrow r \rightarrow 0$  with  $v_0 = v_{rms}$  fixed

$$\epsilon = v_0^3 / l_0$$

Alternative (not necessary): Kolmogorov's 'Second' Universality Assumption: In the limit of infinite Reynolds number, all the small-scale statistical properties are uniquely and universally determined by the scale  $l$  and the mean energy dissipation rate  $\epsilon$ .

(First:  $\frac{4}{5} \epsilon l = \langle u^3 \rangle$ )

i.e. Implications:

$$-\langle \partial v(\ell)^2 \rangle = S_2 \quad ?$$

$$S_2 \sim L^2/T^2, \text{ dimensionally}$$

$$\text{Now } \epsilon \sim L^2/T^3$$

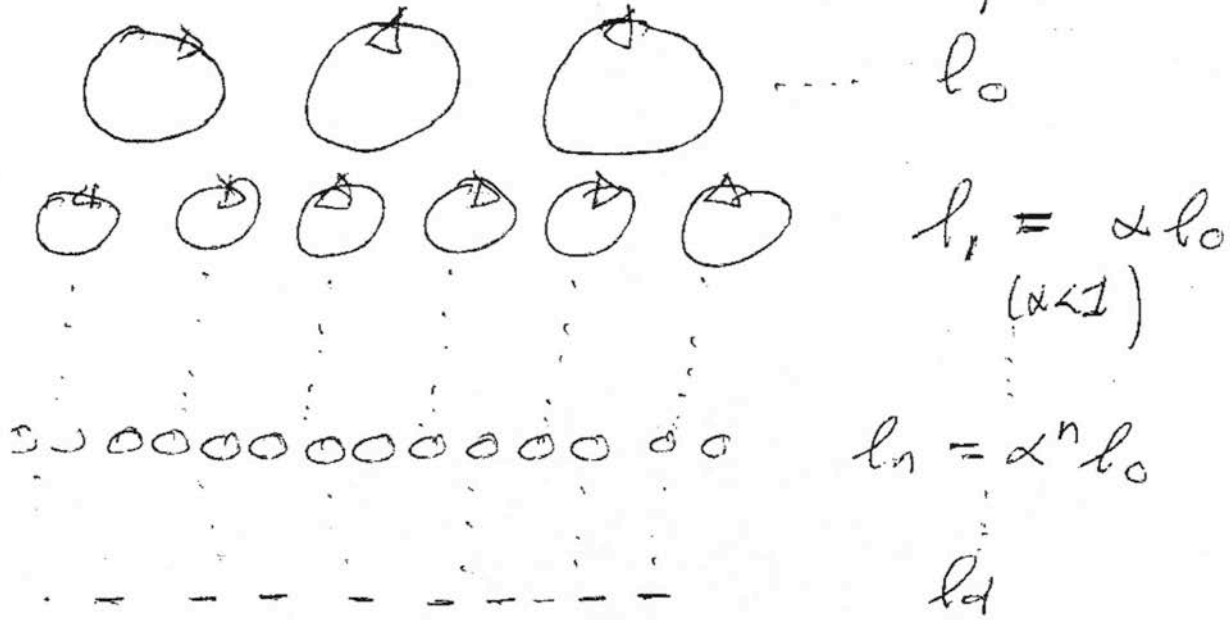
$$\Rightarrow \langle \partial v(\ell)^2 \rangle \sim \epsilon^{2/3} l^{2/3} \Rightarrow \text{recovers } 2/3 \text{ Law.}$$

also, implies  $h = 1/3 \Rightarrow$  scaling exponent, etc.

H1, H2, H3 (2<sup>nd</sup> Universality Assumption)  $\Rightarrow$  KH phenomenology.

K41 Phenomenology

Picture: (Richardson) Cascade / Eddy Mitosis



Key Idea: <sup>①</sup> Flux of energy in 'scale space',  
 from  $l_0$  (integral scale) to  $l_d$ ,  
 (dissipation scale)

<sup>②</sup> energy flux is self-similar  
<sup>③</sup> symmetry restoration.

Flux  $\rightarrow$  <sup>④</sup> energy dissipation  $\rightarrow$  finite limit as  $n \rightarrow \infty$   
 (i.e. endpoint re-adjustment)

self-similarity  $\rightarrow$  2/3 Law

$$S_2 = C (l/l_0)^{2/3}$$

$l_0 \rightarrow \alpha l_0$ ,  $C \rightarrow C \alpha^2$   
 etc.

Ingredients in K41 Phenomenology:

→  $l$  : scale parameter : eddy scale

→  $v(l)$  :  $\tilde{v}(l) \sim \langle \delta v_{ii}(l)^2 \rangle^{1/2}$

↓  
eddy  
velocity

$$\delta v_{ii} \sim \left( \underline{v}(\underline{r} + \underline{l}) - \underline{v}(\underline{r}) \right) \cdot \frac{\underline{l}}{l}$$

≡ longitudinal velocity increment

→  $v_0$  : rms velocity fluctuation  
(large scale dominates)

$$v(l_0) \sim v_0$$

→  $\tau(l)$  : eddy lifetime / turn-over rate  
↓  
characteristic rate of transfer thru  
scale  $l$ .

self-similarity : energy thru-put rate is  
scale  $l$  energy scale invariant

⇒

$$\epsilon = \frac{v(l)^2}{\tau(l)}$$

↓  
dissipation  
rate

energy balance / thru-put  
o.g.

↳ scale  $l$   
life-time

now,  $\tau(l)$  ?

compare  $\tau(l)$  with  $\tau_{2D}(l)$

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$\tau(l) \rightarrow$  'lifetime' of structure of scale  $l$   
 $\rightarrow$  i.e. time for structure to be distorted out of existence

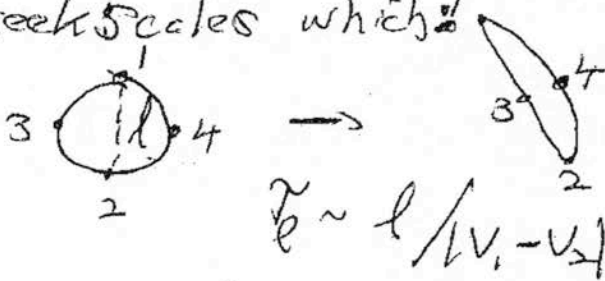
scales  $l' \gg l$  :

$\rightarrow$  advect eddy  $\rightarrow$  apply Galilean boost, but don't affect life-time.  
 irrelevant?  $\rightarrow$  symmetry under random Galilean transformations  
 $\rightarrow$  would also violate symmetry restoration.

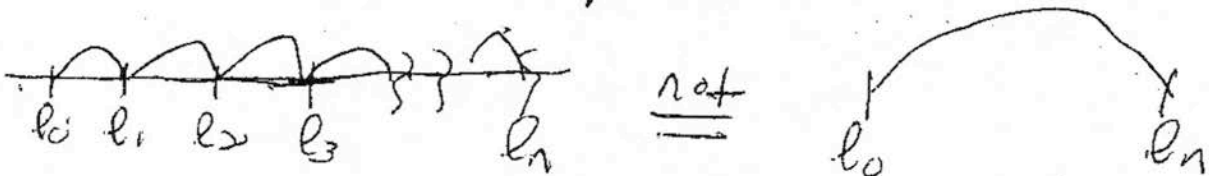
scales  $l \ll l'$  :

$\rightarrow$  irrelevant as very little energy/shear in such eddies/scales

seek scales which



$\rightarrow \tau(l) \sim \frac{l}{v(l)}$  : cascade local in scale space.





$$\epsilon = \frac{v(\ell)^3}{\lambda}$$

$$\Rightarrow v(\ell) \sim (\epsilon \ell)^{1/3} \quad ; \quad \text{K41 scaling relation}$$

$$v(\ell)^3 \sim \epsilon^{2/3} \ell^{2/3}$$

- verifies  $2/3$  Law

- for spectrum:

$$\text{if } E(k) = \dots \quad |v(k)|^2$$

$$\text{s/t } E = \int dk E(k)$$

{ i.e. absorbs density of states

$$\text{then } v(\ell) = \int_{k_{\ell}^{n-1}}^{k_{\ell}^n} dk E(k)$$

$$v(\ell)^3 \sim \epsilon^{2/3} \ell^{2/3} = \epsilon^{2/3} k_{\ell}^{-2/3}$$

$$\Rightarrow E(k) = \epsilon^{2/3} k^{-5/3} \quad ; \quad \text{Kolmogorov Spectrum}$$

at  $l_0$ :

$$v_0 \sim \epsilon^{1/3} l_0 \quad \Rightarrow \quad \frac{v_0^3}{l_0} = \epsilon$$

For dissipation scale:

$l_d$  occurs in  $l$ -space when cascade terminated  
 over viscosity asserts itself  $\rightarrow Re(l) \rightarrow 1$

$$1/Re(l) \sim 1/Re = \nu/l^2$$

$$\Rightarrow \epsilon^{1/3} l^{-2/3} = \frac{\nu}{l^2}$$

$$l^{4/3} = \nu/\epsilon^{1/3} \Rightarrow$$

$$\boxed{l_d = \nu^{3/4} / \epsilon^{1/4}}$$

$$\boxed{l_d \equiv \Lambda, \text{ in Frisch}}$$

Recall:  $\epsilon = \nu \langle (\nabla v)^2 \rangle$

$\Rightarrow \nu \rightarrow 0 \Rightarrow \langle (\nabla v)^2 \rangle$  divergent

$$\langle (\nabla v)^2 \rangle = \int_{k_0}^{k_d} dk k^2 \epsilon^{2/3} k^{-5/3}$$

$$= \int_{k_0}^{k_d} dk k^{1/3} \epsilon^{2/3}$$

$$= k_d^{4/3} \epsilon^{2/3}$$

$$= \frac{\epsilon^{1/3}}{\nu} \epsilon^{2/3} = \epsilon/\nu$$

$\uparrow \downarrow$   
 $\langle (\nabla v)^2 \rangle$  divergent  
 $\nu \rightarrow 0$

## Counting Degrees of Freedom

How big is the inertial range?

$$\begin{aligned} \frac{\Lambda}{l_d} &\sim \frac{l_0}{l_d} \sim \frac{l_0}{(\nu^3/\epsilon)^{1/4}} \\ \# \text{ eddies} &\sim \frac{l_0 (\nu^3/l_0)^{1/4}}{\nu^{3/4}} \sim \left(\frac{\nu l_0}{\nu}\right)^{3/4} \\ &\sim Re^{3/4} \end{aligned}$$

$\therefore$  number of degrees of freedom for 3D turbulence is;

$$N \sim Re^{9/4} \quad ; \quad \begin{array}{l} \text{would be (minimum)} \\ \text{\# grid points to resolve} \\ \text{range of scales in numerical} \\ \text{simulation} \end{array}$$

Now, i.e. atmospheric boundary layer:

$$l_0 \sim 1 \text{ km}$$

$$l_d \sim 1 \text{ mm}$$

$$n \sim 10^6 \Rightarrow \left\{ \begin{array}{l} N \sim 10^{18} \\ Re \sim 10^8 - 10^9 \end{array} \right. \quad \begin{array}{l} | \\ 0 \end{array}$$

$\Rightarrow$  subgrid scale modelling ...

B. : Sometimes able to exploit reduced degrees of freedom models, i.e. when some class of scales slaved to others.

Exercises:

→ Consider passive scalar, with concentration  $C$ :

$$\frac{\partial C}{\partial t} + \underline{v} \cdot \underline{\nabla} C - \kappa \nabla^2 C = \hat{f}_C$$

$C$  dissipation rate in  $\kappa \nabla^2$  turbulence  $\equiv \alpha$

i.e.  $\alpha = \overline{\epsilon}_C^2 \frac{v_0}{l_0}$

- ⇒ a) Calculate  $\kappa \nabla^2$  spectrum for  $C$ ,  
 Discuss  
 b) What if  $\kappa \ll \nu$  ?  
 $\gg$

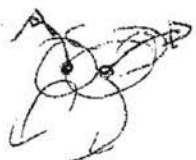
→ Consider incompressible turbulence with  
 $M \equiv \frac{v_0}{c_s} \ll 1$ .

Show:  $\frac{l_d}{l_{\text{max}}} \sim M^{-1} Re^{1/4}$

⇒ validity of continuum hydrodynamics gets better at high  $Re$ .

Particle Separation / Richardson Law

Consider 2 particles (test) in K41 turbulence.  
Rate of separation?



- larger eddys advect both
- smaller eddys do @ nothing

⇒ divergence controlled by eddys of scale  $l \sim |x_1 - x_2|$ .

∴ if  $\lambda \equiv |x_1 - x_2|$

$$\Rightarrow \frac{d\lambda}{dt} = v(\lambda) = \epsilon^{1/3} \lambda^{1/3}$$

$$\lambda^{2/3} = \epsilon^{1/3} t$$

$$\therefore \lambda \sim \epsilon^{1/2} t^{3/2}$$

Richardson's 3/2 Law

N.B.: Non-diffusive!

$$\lambda^2 \sim \epsilon t^3 \Rightarrow \tau_{sep.} \sim \lambda^{2/3} / \epsilon^{1/3}$$

N.B.:

→ process is self-accelerating ⇒ large eddys move faster

non-diffusive.

→ [Momentum] Flux Driven  
Turbulence

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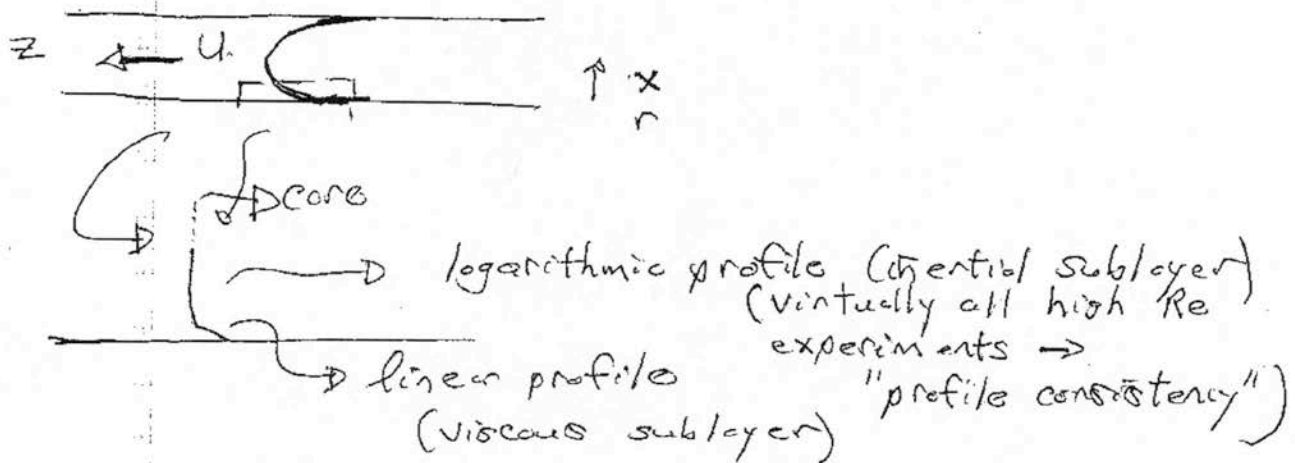
↳ Turbulent Pipe Flow

(cf. Landau, Lifshitz "Fluid Mechanics")

Full flow → homogeneous flow in a periodic box  
→ cascade in scale space (Kolmogorov)

Now → inhomogeneous flow in a pipe  
→ momentum transport in a turbulent boundary layer (Prandtl)

Consider turbulent pipe flow:



Common features of pipe flow:

- linear → logarithmic  $U(x)$  profile
- logarithmic profile persists over a broad range of  $Re$

$$(Re = 2Ua/\nu)$$

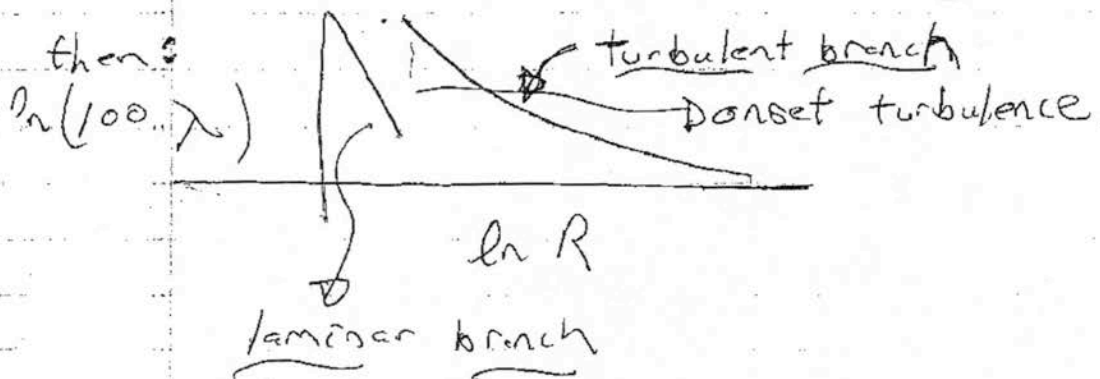
• logarithmic profile "universal" (Prandtl "Law of the Wall")

- resistance <sup>increases</sup> with increasing  $Re$ ,  
 dis continuously  $\rightarrow$  pressure drop/length

$$\lambda = 2a \Delta p / l$$

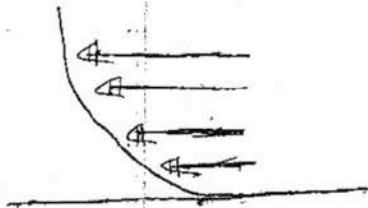
$$\frac{1}{2} \rho U^2$$

$\hookrightarrow$  mean flow energy



- turbulent resistance curve universal.

• What is going on?



no slip boundary condition  
 $u = u(x) \rightarrow 0$   
 $x \rightarrow 0$

$\therefore u = u(x) \Rightarrow$  { momentum flux to wall }



→ momentum flux to wall  $\Rightarrow$  stress on the wall

→ wall stress must balance pressure drop, for steady flow

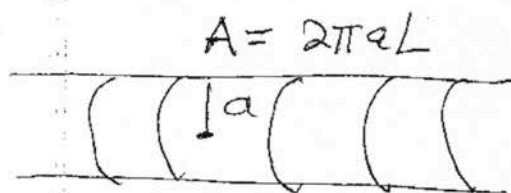
so wall stress  $\propto U_*^2$   
 $U_* \equiv$  friction velocity

i.e.

$$\frac{\rho U_*^2}{F \sim \rho U_*^2} \sim \frac{\Delta p}{\rho} \sim \frac{\Delta p}{\rho} \frac{l}{R}$$

$$\rho U_*^2 l R \sim \Delta p \pi R^2$$

$$\rho U_*^2 2\pi a l = \Delta p \pi a^2$$



$\Delta l$

$\Delta p$

$\delta$   
pressure drop

Force on wall  $\approx$   
 $\rho U_*^2 A_{\text{wall}}$

(Pressure Drop)  $A_{\text{flow}}$

$=$  Force on Fluid

friction velocity  $\Rightarrow \rho U_*^2 (2\pi a l) = (\Delta p) \pi a^2$

$$U_* = \left[ \frac{(\Delta p / 2\rho) (a)}{2l} \right]^{1/2}$$

Friction Velocity

$U_* \equiv$  friction velocity  
 $\equiv$  "typical" velocity of turbulence in turbulent pipe

Deriving the inertial sublayer profile:

i) dimensional reasoning

in pipe flow inertial sublayer, have

3 dimensional parameters  $\rho$ ,  $\tau_w$ ,  $x$

$\left. \begin{array}{l} \rho \\ \tau_w \end{array} \right\} \begin{array}{l} \text{density} \\ \text{wall stress} \end{array}$

$x \rightarrow$  distance from wall

Key Point: ~~Assumption~~  
 at scale invariance

on scale  $l_{vs} = \frac{\nu}{U_*} < x < a$

$\rightarrow$  universality of logarithmic profile motivated scale invariance assumption

now, seek velocity gradient  $dU/dx$ ,

$\frac{dU}{dx} : U_*, x, \rho$

so simplest form for  $dU/dx$  is:

$$\frac{dU}{dx} = \frac{U_*}{x}$$

$$\Rightarrow \left\{ \begin{aligned} U &= \frac{U_*}{K} \ln(x/x_0) \\ &= \frac{U_*}{K} \ln x + \text{const.} \end{aligned} \right.$$

→ logarithmic profile (consequence of scale invariance in pipe flow)

→  $K \approx 4$  universal constant → von-Karman constant

→  $x_0 \leftrightarrow$  width of viscous sublayer  $\sim \nu/U_*$

(ii) Physical Reasoning

stationary flow  $\Rightarrow$

Momentum flux to wall = pressure drop

$$\langle \tilde{v}_x \tilde{v}_z \rangle = U_x^2$$

↓  
Reynolds stress

$$\rho \langle \tilde{v}_x \tilde{v}_z \rangle = \tau_p$$

↳ momentum flux

$$\tau_p / \rho = U_x^2$$

Now, to calculate  $\langle \tilde{v}_x \tilde{v}_z \rangle$ :

→ take velocity fluctuation as generated by mixing of  $U(x)$ , so

$$\Rightarrow v_z \sim l \frac{\partial U}{\partial x}$$

↓  
"mixing length"

analogous to Chapman-Enskog expansion, i.e.

$$l \Leftrightarrow l_{\text{mix}}$$

$$U_x \Leftrightarrow U_{\text{th}}$$

here, scale invariance ~~is~~  $l \sim x$

mixing length set by  
distance from wall

$$\begin{aligned} \text{so } \langle \overline{v_x v_x} \rangle &= \langle v_x l \rangle \frac{\partial U}{\partial x} \\ &\approx U_* x \frac{\partial U}{\partial x} \end{aligned}$$

$\tau_T = U_* x \rightarrow$  "eddy viscosity"  
"turbulent viscosity"  $\rightarrow$  key concept.

$\Rightarrow$  rate of turbulent transport  
of momentum

then momentum balance  $\Rightarrow$

$$U_* x \frac{\partial U}{\partial x} = U_*^2$$

$$\Rightarrow U = \frac{U_*}{K} \ln(x/x_0) \rightarrow \text{Logarithmic Profile}$$

$\rightarrow$  Law of the Wall

Some comments:

→ as in k41, clear phenomenology critical to guiding the approximations → scale invariance

⇒ "Mixing length theory always works... provided you know the mixing length..."  
- P. D.

⇒ why a single value of velocity, i.e.  $U_*$ ?

Consistent with mixing length hypothesis, velocity fluctuations generated by mixing of mean flow gradient, i.e.

$$\Rightarrow \tilde{v} \sim l \frac{\partial U}{\partial x} \sim x \frac{\partial U}{\partial x}$$

~~$$\sim \frac{U_*}{x}$$~~

absence of preferred scale.

consistent. ⇒ Assumption consistent with:  
- logarithmic profile  
- scale invariance.

→ viscous sublayer / cut-off of inertial layer?

∴ when:  $\nu_T < \nu$

{ molecular viscosity  
dominates mixing

$$\Rightarrow u_* x \lesssim \nu$$

$$x \lesssim \nu / u_* \equiv x_0$$

{  
viscous sublayer  
scale.

In viscous sublayer, flow linear:

$$\nu \frac{\partial u}{\partial x} = u_*^2$$

$$\therefore u = \frac{u_*^2}{\nu} x$$

⇒ note effect of turbulence is to:

- flatten profile - { higher transport at fixed  
wall stress
- reduce central velocity
- limit  $Q$  (quality factor)



- matching, far const:

$$x_0 = \nu / U_* \quad \text{so}$$

$$U = \frac{U_*}{K} \ln \left( \frac{U_* y}{\nu} \right)$$

Note: Flow in viscous sublayer is turbulent, but mixing there affected by dissipation range scales  $\Rightarrow$  linear profile

Now - turbulent dissipation  $\rho$ .

Consider NSE:

$$\begin{aligned} \frac{\partial \hat{v}}{\partial t} + \hat{v} \cdot \nabla \hat{v} + \langle \hat{v}_z \rangle \frac{\partial \hat{v}}{\partial z} + \hat{v}_x \frac{\partial \langle v_z \rangle}{\partial x} \\ = -\nabla \hat{p} + \nu \nabla^2 \hat{v} \end{aligned}$$

$\hat{v}$  and avg  $\Rightarrow$

$$\frac{\partial \langle \hat{v}^2 \rangle}{\partial t} + \langle \hat{v} \cdot \hat{v} \cdot \nabla \hat{v} \rangle + \langle v_z \rangle \langle \hat{v} \cdot \frac{\partial \hat{v}}{\partial z} \rangle$$

$$+ \langle \hat{v}_x \hat{v}_z \rangle \frac{\partial \langle v_z \rangle}{\partial x} = - \underbrace{\langle \hat{v} \cdot \nabla \hat{p} \rangle}_{i.b.p} - \nu \langle \nabla^2 \hat{v}^2 \rangle$$

input  $\rightarrow$  mean flow mixing 276

obviously:  $\nu \langle (\nabla \cdot \vec{v})^2 \rangle = \nu_T \left( \frac{\partial U}{\partial x} \right)^2$   
small scale dissipation

and

$$\begin{aligned} \epsilon &= (U_T X) \left( \frac{U_T}{X} \right)^2 \quad (\text{ignoring } R) \\ &= \frac{U_T^3}{X} \end{aligned}$$

$\rightarrow$  sets dissipation rate

i.e.  $\epsilon = \frac{V_0^3}{l}$        $V_0 \leftrightarrow U_T$   
 $l \leftrightarrow X$

$\rightarrow \epsilon$  finite as  $\nu \rightarrow 0$  (i.e. viscous sublayer gradient diverges then)

### Additional References:

- S.B. Pope, "Turbulent Flows"
- H. Tennekes and J. Lumley, "A First Course in Turbulence"

For net energy budget:

$$\partial_t \mathcal{E} = - \underbrace{\langle \tilde{u}_x \tilde{v}_z \rangle}_{\substack{\downarrow \\ \text{input to fluctuations} \\ \text{by relaxation of} \\ \text{mean shear flow} \\ \text{(Reynolds work)}}} \frac{\partial \langle v_z \rangle}{\partial x} - \nu \underbrace{\langle (\tilde{u}^2)^2 \rangle}_{\substack{\downarrow \\ \text{dissipation} \\ \text{of fluctuations} \\ \text{energy by viscosity}}}$$

∴ can define:

$$\mathcal{E} = \underbrace{\langle \tilde{u}_x \tilde{v}_z \rangle}_{\substack{\downarrow \\ \text{turbulent} \\ \text{dissipation} \\ \text{rate}}} \frac{\partial U}{\partial x}$$

and using mixing length theory:

$$\langle \tilde{u}_x \tilde{v}_z \rangle = u_T x \frac{\partial U}{\partial x}$$

$$\Rightarrow \mathcal{E} = (u_T x) \left( \frac{\partial U}{\partial x} \right)^2 = \gamma_T \underbrace{\left( \frac{\partial U}{\partial x} \right)^2}_{\substack{\downarrow \\ \text{rate of "heating" by} \\ \text{turbulent relaxation} \\ \text{of mean flow.}}}$$



→ Now, interesting to tabulate comparison between Pipe Flow and K41 Problem

Pipe Flow (Prandtl)	K41 (Kolmogorov)
<u>scales</u> : $a, x, \nu/u_*$ <u>invariance</u> : $x \rightarrow$ real space	$l_0, l_n, l_d$ $l \rightarrow$ scale space
inertial sublayer viscous sublayer	inertial range dissipation range
<u>balance</u> : $u_*^2 = \nu_T \frac{\partial u}{\partial x}$	$\epsilon = \frac{v(l)^3}{T(l)}$
<u>dynamics</u> : eddy viscosity $\nu_T = u_* x$	turn-over rate $1/T(l) = \frac{v(l)}{l}$
<u>result</u> : $u = \frac{u_*}{R} f(x)$	$v(l) = \epsilon^{1/3} l^{1/3}$
<u>universal profile</u>	<u>universal spectral scaling</u>
<u>dissipation</u> : $\nu = \nu_T$ $x_0 = \nu/u_*$	$v(l)/l = \nu/l^2$ $l_d = \nu^{3/4} / \epsilon^{1/4}$

→ Practical Issues

Resistance Law  $\leftrightarrow$  Pipe Flows.

have:  $\frac{v}{u_*} < \chi < a$   
 $\downarrow$   
 radius

can push to  $\chi \approx a$ , with logarithmic accuracy.

$$U \approx \frac{u_*}{R} \ln \left( \frac{u_* a}{v} \right)$$

but

$$u_* = U_* = \left( \frac{a \Delta P}{\ell 2\rho} \right)^{1/2}$$

⇒ can re-write:

$$U = \left( \frac{a \Delta P}{2\rho \ell R^2} \right)^{1/2} \ln \left( a \left( \frac{a \Delta P}{2\rho \ell} \right)^{1/2} / v \right)$$

Convenient to define:

$$\chi = \frac{2a \Delta P / \ell}{\frac{1}{2} \rho U^2}$$

↳ flow KE

→ friction / resistance  
Factor / Coefficient

$$\Rightarrow \text{taking } Re = 2aU/v$$

can re-write friction law as:


$$\left\{ \begin{array}{l} 1/\sqrt{\lambda} = .88 \ln(Re\sqrt{\lambda}) - .80 \\ Re = 2aU/v \end{array} \right. \quad \begin{array}{l} \downarrow \\ \text{phenom.} \end{array}$$

$$\lambda = \frac{2a \Delta p / \ell}{\frac{1}{2} \rho U^2}$$

→ good fit to pipe flow data.

Problems:

1a.) A very strong explosion, with energy released  $\Delta E$ , creates a spheroidal blast wave in an atmosphere of pressure  $P_0$ , density  $\rho$ . Use dimensional analysis to derive the radius of the blast front as a function of time, i.e.  $r(t)$ ? When does this scaling fail?

b.)  A hot surface produces thermal convection above it. Assuming the convection is turbulent, use scaling arguments to calculate the temperature profile above the plate, assuming the hot plate drives a surface heat flux  $Q$ . (See Chapter 5; Landau).



Why Wave "kinetics"?

" A wave is never found alone, but is mingled with as many other waves as there are uneven places in the object where the said wave is produced. At one and the same time there will be moving over the greatest wave of a sea innumerable other waves proceeding in different directions "

- Leonardo da Vinci  
Codice Atlantico, c.1500.



From Asian art...

The great wave at Kanagawa Hokusai

