

II.) Technical Aside: IMPORTANT

- Where does CGL come from?
- Why is it so $\ast \int \sqrt{x}$ ubiquitous?

Consider nonlinear oscillator:

$$\ddot{x} + \omega_0^2 x = f(x, \dot{x}) + \epsilon p(t)$$

\downarrow oscillator \downarrow nonlinearity \downarrow forcing \rightarrow frequency ω

seek: $x(t) = \frac{1}{2} (A(t) e^{i\omega t} + \text{c.c.})$

\downarrow amplitude \downarrow "entraining" frequency
 (not necessarily slow \rightarrow i.e. phase jumps)

Now, then convenient to re-write:

$$\ddot{x} + \omega^2 x = (\omega^2 - \omega_0^2)x + f(x, \dot{x}) + \epsilon p(t)$$

or $\dot{x} = y$

$$\dot{y} = -\omega^2 x + (\omega^2 - \omega_0^2)x + f(x, y) + \epsilon p(t)$$

so if $y = \frac{1}{2} (i\omega A(t) e^{i\omega t} + c.c.)$
 $(y = \dot{x})$

then: Amplitude Eqn \leftrightarrow Complex A

$$* \quad \dot{A}(t) = \frac{e^{-i\omega t}}{i\omega} \left[(\omega^2 - \omega_0^2)x + f(x, y) + \epsilon p(t) \right]$$

} Amplitude
} mis-match
} nonlinearity
} forcing

Now, as usual:

- interested in slowest, largest variations on RHS
 \Rightarrow isolate slowest terms

- eliminate fast oscillations via averaging
 (akin method of averaging)

To Average:

- substitute x, y in terms $A(t)$ on RHS of $*$
- neglect oscillating terms (on ω scale)

$$\dot{A} = \frac{e^{-i\omega t}}{i\omega} \left[\overset{\textcircled{1}}{(\omega^2 - \omega_0^2)x} + \overset{\textcircled{2}}{f(x, y)} + \overset{\textcircled{3}}{\epsilon p(t)} \right]$$

①:

$$\begin{aligned} \dot{A}(t) &= \int_0^{2\pi/\omega} d\tau \frac{e^{-i\omega\tau}}{i\omega} \left[(\omega^2 - \omega_0^2) \left(\frac{1}{2} A(t) e^{i\omega\tau} + \text{c.c.} \right) \right] \\ &= \frac{(\omega^2 - \omega_0^2)}{2i\omega} A(t) \end{aligned}$$

②:

$$A(t) = \int_0^{2\pi/\omega} d\tau \frac{e^{-i\omega\tau}}{i\omega} f(x, y)$$

Now, $f(x, y)$ is nonlinear, in general,

$$f(x, y) = \sum_{m, n} C_{m, n} (A e^{i\omega t})^n (A^* e^{-i\omega t})^m$$

$$\Rightarrow A_{\omega} = \int_0^{2\pi} d\tau \frac{e^{-i\omega\tau}}{i\omega} \sum_{m, n} C_{m, n} (A e^{i\omega t})^n (A^* e^{-i\omega t})^m$$

only $n - m - 1 = 0$ don't vanish
 (extracts phase coherent
 piece of nonlinearity
 coherent with $e^{i\omega t}$)
 $m = n - 1$

Thus A_{ω} must have form:

$$A_{\omega} = g(|A|^2) A \quad \left(\text{i.e. only } \neq \text{ phase} \right)$$

\downarrow
 arbitrary (set by problem)

simplest choice: $g(|A|^2) = \mu - \gamma |A|^2$

$$g(|A|^2) A = \underbrace{\mu A}_{\substack{\text{linear} \\ \text{term} \\ \text{(growth)}}} - \underbrace{(\gamma + iK) |A|^2 A}_{\substack{\text{lowest n.l. term} \\ \Rightarrow \\ \text{(saturation)}}$$

$\mu, \gamma > 0 \Rightarrow$ supercritical bifurcation

$\mu, \gamma < 0 \Rightarrow$ sub-critical bifurcation \Rightarrow need h.o. to saturate.

Similarly, we have:

$$P(A) = \sum_n (p_n e^{in\omega t} + \text{c.c.})$$

$$\int_0^{2\pi/\omega} d\tau \frac{e^{-i\omega\tau}}{i\omega} \epsilon P(t) = -i\epsilon E$$

so

$$\dot{A} = \underbrace{-i \frac{(\omega^2 - \omega_0^2)}{2\omega}}_{\text{mismatch}} A + \underbrace{\mu A}_{\text{growth}} - \underbrace{(\gamma + iK) |A|^2 A}_{\substack{\text{NL saturation} \\ \text{NL freq shift}}} - \underbrace{i\epsilon E}_{\text{drive}}$$

\Rightarrow recovers CGL structure!

Note:

- derivation is "generic" to form of nonlinear oscillator.

- in general: $g(|A|^2) = \sum_n g_n (|A|^2)^n$

with coeffs set by problem.

- not surprisingly, can also describe via method of reductive perturbation theory (i.e. Poincaré-Lindstedt).
- in absence of forcing, recovers Landau-Stuart:

$$\frac{dA}{dt} = (i + \mu) A - (1 + i\alpha) |A|^2 A$$

- for validity, need:

$$|\omega - \omega_0| \ll \omega_0$$

$$\mu \ll \omega_0$$

} ensure

- NL term small

- weak instability of $A=0$ fixed point

Note: Story is consistent, i.e.

μA vs $\gamma |A|^2 A$ ensures:

$$\underline{\text{so}} \quad |A|^2 \lesssim \mu / \gamma \Leftrightarrow NL \sim L$$

\Leftrightarrow requires small growth. In practice, CGL valid only near marginality.