

# PHYS 201 Mathematical Physics, Fall 2017, Homework 6

Due date: Thursday, November 30th, 2017

The first part of the homework is a review on some exact methods to solve ordinary differential equations. Read Chapter 1 of the book by Bender and Orszag for a more detailed version. For this section, you may turn in only the final answer for each problem; the derivation is not necessary. For the questions on approximate solutions, the full derivation is required.

*Terminology:* A linear(L) ODE is of the form  $Ly(x) = f(x)$ , where  $L$  is a differential operator

$$L = p_0(x) + p_1(x)\frac{d}{dx} + \cdots + p_{n-1}(x)\frac{d^{n-1}}{dx^{n-1}} + \frac{d^n}{dx^n}$$

If  $f \equiv 0$ , the differential equation is called homogeneous (H), otherwise it's an inhomogeneous (IH) differential equation. An  $n$ -th order homogeneous linear equation (H,L,n) has  $n$  linearly independent solutions  $y_i(x), i = 1, 2, \dots, n$ . The Wronskian  $W(x) = W[y_1(x), y_2(x), \dots, y_n(x)]$  is used to test the linear independence of the solutions  $\{y_i(x)\}$ . Here

$$W(x) = \det \begin{vmatrix} y_1 & y_2 & \cdots & y_n \\ y_1' & y_2' & \cdots & y_n' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \cdots & y_n^{(n-1)} \end{vmatrix}$$

If the Wronskian is non-zero except at isolated points, the solution set  $\{y_i(x)\}$  is linearly independent. The Wronskian can also be found using Abel's formula,  $W(x) = \exp \left[ - \int^x p_{n-1}(t) dt \right]$ .

1. *Constant-coefficient H,L,n ODEs:* If  $p_i$ 's are constants, then substitute  $y = e^{rx}$  and solve for the polynomial in  $r$ . If the root  $r$  is repeated  $m$  times, then the solutions are of the form  $e^{rx}, xe^{rx}, \dots, x^{m-1}e^{rx}$ .

i. Solve  $y''' - 4y'' + 5y' - 2y = 0$ .

2. *Equidimensional-in-x:* If the equation is invariant under the transformation  $x \rightarrow ax$ , substitute  $x = e^t$  and it turns into a constant-coefficient equation.

3. *Exact equations:* If a first-order equation can be written as

$$M[x, y(x)] + N[x, y(x)]y'(x) = \frac{d}{dx}f[x, y(x)] = 0$$

then the equation is exact (and the solution is  $f = c$ ). A first-order equation is exact iff

$$\frac{\partial}{\partial y}M(x, y) = \frac{\partial}{\partial x}N(x, y)$$

A higher order H,L equation can be converted to a lower order equation if we can observe that  $Ly = 0 \Rightarrow \frac{d}{dx}(My) = 0$  where  $M$  is an L differential operator of one less order.

- i. Use the integrating factor  $e^{xy}$  and verify that the equation  $(1 + xy + y^2) + (1 + xy + x^2)y'(x) = 0$  is exact.
- ii. Solve  $yy'' + y'^2 - yy'/(1 + x) = 0$ .

4. *Reduction of order for L equations:* The order of any L equation can be reduced if one of the solution  $y_1(x)$  is known by substituting  $y(x) = u(x)y_1(x)$ .

- i. Solve  $y'' + (x + 2)y' + (1 + x)y = 0$ .

5. *Integrating factor for IH,L,1 equations:* All IH,L,1 equations can be solved using the integrating factor  $I(x) = \exp[\int^x p_0(t)dt]$ . The solution is

$$y(x) = \frac{c}{I(x)} + \frac{1}{I(x)} \int^x f(t)I(t)dt$$

- i. Solve  $y' + 2y = e^{3x}$ .

6. *Variation of Parameters technique for IH,L,2 equations:* For every IH,L,2 equation  $Ly = f$ , if  $y_1(x)$  and  $y_2(x)$  are the solutions for the H,L,2 equation  $Ly = 0$  and  $W(x) = W[y_1(x), y_2(x)]$  is the Wronskian, then the solution  $y(x)$  is given by

$$y(x) = -y_1(x) \int^x \frac{f(t)y_2(t)}{W(t)}dt + y_2(x) \int^x \frac{f(t)y_1(t)}{W(t)}dt$$

This technique can be generalized to higher order IH,L equations.

- i. Solve  $y'' + 6y + 9 = \cosh(x)$ .

7. *Bernoulli equations:* Bernoulli equations are NL,1 equations and have the form

$$y' = a(x)y + b(x)y^P$$

They can be converted to L equations using the substitution  $u(x) = y(x)^{1-P}$ .

i. Solve  $-xy' + y = xy^2, y(1) = 1$ .

8. *Riccati equations*: These are NL,1 equations of the form

$$y'(x) = a(x)y^2(x) + b(x)y(x) + c(x)$$

They can be solved by guessing one particular solution  $y_1(x)$  and substituting  $y(x) = u(x) + y_1(x)$ . This converts the Riccati equation to a Bernoulli equation and the general solution can be found thereafter.

i. Solve  $xy' - 2y + ay^2 = bx^4$ .

9. *Substitutions*: Sometimes a good substitution can convert an NL equation to an equation that is easily solvable.

i. Solve  $y' = x^2 + 2xy + y^2$ .

10. *Autonomous NL equations*: Autonomous equations are those in which the independent variable (in our case  $x$ ) does not appear. The order of autonomous equations can be reduced to a lower order equation in  $y$  by using  $y' = u(y), y'' = \frac{du}{dx} = u'(y)u(y)$  and so on.

i. Reduce the order and solve, if possible, the Blasius equation  $y''' + yy'' = 0$ .

11. *Scale-invariant NL equations*: If the transformations  $x \rightarrow ax$  and  $y \rightarrow a^P y$  leave the equation unchanged, then the equation is scale-invariant. The substitution  $y(x) = x^P u(x)$  converts a scale-invariant equation to an equidimensional equation in  $x$  (which can be turned into an autonomous equation using  $x = e^t$ ).

i. Reduce the order and solve, if possible,  $xyy'' = yy' + xy'^2$ .

12. *Equidimensional-in-y NL equations*: If the equation is unchanged by the transformation  $y \rightarrow ay$ , then the substitution  $y(x) = e^{u(x)}$  reduces the order of the equation by one.

i. Reduce the order by one of  $x^2yy'' + xy'y'' + yy' = 0$ .

### Approximate solutions to H,L ODEs:

13. Find the Frobenius series expansion about  $x = 0$  of the solutions of the equation

$$2xy'' - y' + x^2y = 0$$

14. Find the full asymptotic behavior of the parabolic cylinder functions  $D_\nu(x)$  as  $x \rightarrow \infty$ . The parabolic cylinder functions satisfy the differential equation

$$y'' + \left( \nu + \frac{1}{2} - \frac{x^2}{4} \right) y = 0$$

i. By substituting  $y = e^{S(x)}$  in the differential equation and assuming  $S'' \ll (S')^2, x \rightarrow \infty$ , show that the two possible leading behaviors for the solution are

$$y(x) \sim c_1 x^{-\nu-1} e^{x^2/4}$$

$$y(x) \sim c_2 x^\nu e^{-x^2/4}$$

$D_\nu(x)$  is defined as the second equation with  $c_2 = 1$ . We have  $D_\nu(x) = x^\nu e^{-x^2/4} w(x)$  where  $w(x) = 1 + \epsilon(x), \epsilon(x) \ll 1$  as  $x \rightarrow \infty$ .

ii. Find the leading behavior of  $\epsilon(x)$  of the form  $a_1 x^{-\alpha}$  by substituting  $D_\nu(x)$  back in the differential equation and solving the resulting differential equation in  $\epsilon$  for large  $x$  (make appropriate approximations).

iii. Find the full asymptotic solution for  $\epsilon(x)$  by substituting  $\epsilon(x) = \sum_{n=1}^{\infty} a_n x^{-n\alpha}$  and solving the recurrence relation for  $a_n$ . Show that the series truncates if  $\nu$  is a nonnegative integer (Observe that the parabolic cylinder equation for nonnegative integer  $\nu$  is the Schrodinger's equation for the quantum harmonic oscillator. The solutions are known to be of the form  $e^{-x^2/4} \text{He}_\nu(x)$  i.e., the series solution found above generates the Hermite polynomials).

iv. For  $\nu = 4.5$ , calculate the number of terms in the optimal asymptotic approximation at  $x = 0.5$  and  $x = 5$ .

15. Analyze the asymptotic behavior of the first Airy function  $\text{Ai}(x)$  as  $x \rightarrow \infty$ . The Airy equation is

$$y'' = xy$$

i. Find the two possible leading behaviors of the solutions using ideas from Exercise 14.  $\text{Ai}(x)$  is defined as the solution whose leading behavior is  $y(x) \sim \frac{1}{2\sqrt{\pi}} x^{-1/4} e^{-2x^{3/2}/3}, x \rightarrow \infty$ .

ii. Find the full asymptotic behavior i.e., the series solution to  $w(x) = 1 + \epsilon(x)$  (as defined in 14) by directly substituting  $w(x) = \sum_{n=0}^{\infty} a_n x^{-n\alpha}, \alpha > 0, a_0 = 1$  and solving for  $\alpha$  and the obtained recurrence relation.

iii. Find the number of terms in the optimal asymptotic approximation for  $x = 5$ .