

1. Principle of Least Action:

$$\delta \int L dt = 0$$

By  $L = p\dot{q} - H$ ,

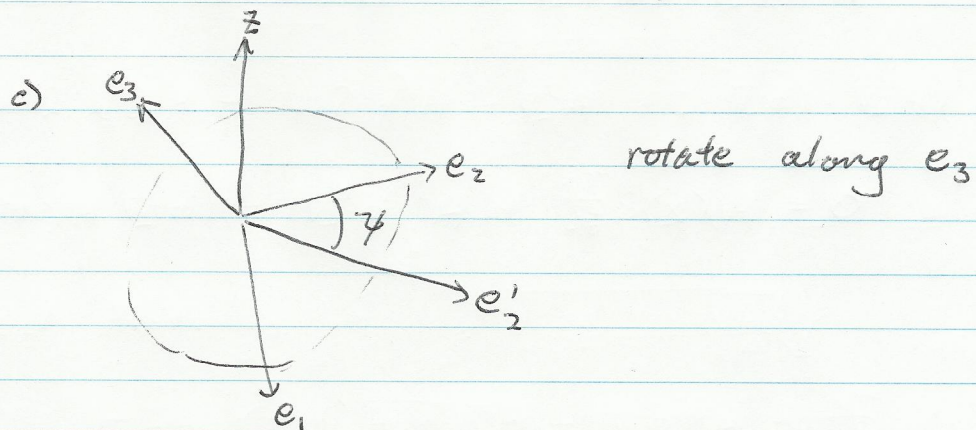
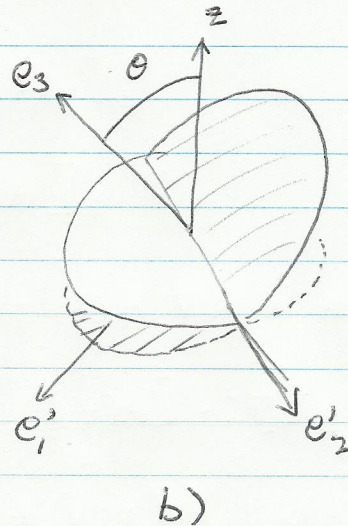
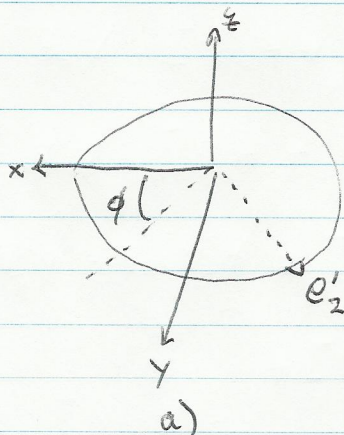
we have  $0 = \delta \int p dq - \delta \int H dt$

$$= \int \delta p \frac{dq}{dt} dt + \int p \delta dq - \int \delta H dt - \int H \delta t$$

$$= \int dt \left[ \delta p \dot{q} - \delta q \dot{p} - \frac{\partial H}{\partial p} \delta p - \frac{\partial H}{\partial q} \delta q - \frac{\partial H}{\partial t} \delta t + \frac{\partial H}{\partial t} \delta t \right]$$

$\Rightarrow \dot{q} = \frac{\partial H}{\partial p}$  and  $\dot{p} = -\frac{\partial H}{\partial q}$  by matching  $\delta p$ ,  $\delta q$  terms.

## 2 Euler Angles



$$\Rightarrow \vec{\omega} = \dot{\phi} \hat{z} + \dot{\theta} \hat{e}'_2 + \dot{\psi} \hat{e}_3$$

Since  $\hat{z} = \cos \theta \hat{e}_3 - \sin \theta \hat{e}'_1$  (refer to fig b)

$$\Rightarrow \vec{\omega} = -\dot{\phi} \sin \theta \hat{e}'_1 + \dot{\theta} \hat{e}'_2 + (\dot{\psi} + \dot{\phi} \cos \theta) \hat{e}_3$$

As angular momentum  $L$  is  $(\lambda_1 \omega_1, \lambda_2 \omega_2, \lambda_3 \omega_3)$   
for set of principle axes,

$$\vec{L} = -\lambda_1 \dot{\phi} \sin \theta \hat{e}'_1 + \lambda_2 \dot{\theta} \hat{e}'_2 + \lambda_3 (\dot{\psi} + \dot{\phi} \cos \theta) \hat{e}_3$$

where  $\lambda_1 = \lambda_2$  for symmetric top.

2 Cont'd  
Thus,

$$T = \frac{1}{2} \lambda_1 (\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2) + \frac{1}{2} \lambda_3 (\dot{\psi} + \dot{\phi} \cos \theta)^2$$

$$U = M_g R \cos \theta$$

$$p_\theta = \frac{\partial T}{\partial \dot{\theta}} = \lambda_1 \dot{\theta}, \quad p_\psi = \frac{\partial T}{\partial \dot{\psi}} = \lambda_3 (\dot{\psi} + \dot{\phi} \cos \theta)$$

$$p_\phi = \frac{\partial T}{\partial \dot{\phi}} = \lambda_1 \dot{\phi} \sin^2 \theta + \lambda_3 (\dot{\psi} + \dot{\phi} \cos \theta) \cos \theta \\ = \lambda_1 \dot{\phi} \sin^2 \theta + p_\psi \cos \theta$$

$$\Rightarrow T = \frac{(\lambda_1 \dot{\phi} \sin^2 \theta)^2}{2 \lambda_1 \sin^2 \theta} + \frac{p_\theta^2}{2 \lambda_1} + \frac{p_\psi^2}{2 \lambda_3} \\ = \frac{(p_\phi - p_\psi \cos \theta)^2}{2 \lambda_1 \sin^2 \theta} + \frac{p_\theta^2}{2 \lambda_1} + \frac{p_\psi^2}{2 \lambda_3}$$

$$\Rightarrow H = \frac{(p_\phi - p_\psi \cos \theta)^2}{2 \lambda_1 \sin^2 \theta} + \frac{p_\theta^2}{2 \lambda_1} + \frac{p_\psi^2}{2 \lambda_3} + M_g R \cos \theta$$

Hamilton Equations:

$$\dot{\phi} = \frac{\partial H}{\partial p_\phi} = \frac{p_\phi - p_\psi \cos \theta}{2 \lambda_1 \sin^2 \theta}, \quad \dot{\theta} = \frac{\partial H}{\partial p_\theta} = \frac{p_\theta}{\lambda_1}$$

$$\dot{\psi} = \frac{\partial H}{\partial p_\psi} = - \frac{p_\phi - p_\psi \cos \theta}{2 \lambda_1 \sin^2 \theta} \cos \theta + \frac{p_\psi}{\lambda_3}$$

$$\dot{p}_\phi = \dot{p}_\psi = 0$$

$$\dot{p}_\theta = - \frac{\partial H}{\partial \theta} = M_g R \sin \theta //$$

$$4a) \nabla^2 \psi - \frac{1}{c(x)^2} \frac{\partial^2 \psi}{\partial t^2} = 0$$

As the equation has no explicit  $t$  dependence,  
we let

$$\psi \rightarrow \psi_0 e^{-i\omega t}$$

$$\Rightarrow \nabla^2 \psi_0 + \frac{\omega^2}{c^2} \psi_0 = 0$$

We further let  $\psi_0 = A e^{i\Phi(x)}$

where  $\left| \frac{\nabla \Phi}{\Phi} \right| \gg \left| \frac{\nabla A}{A} \right|$  (limit of geometric optics)

$$\text{Since } \nabla \psi_0 = (\nabla A + i \nabla \Phi A) e^{i\Phi}$$

$$\begin{aligned} \nabla^2 \psi_0 &= \nabla \cdot \nabla \psi_0 = i \nabla \Phi \cdot (\nabla A + i \nabla \Phi A) e^{i\Phi} \\ &\quad + e^{i\Phi} (\nabla^2 A + i \nabla^2 \Phi A + i \nabla \Phi \cdot \nabla A) \end{aligned}$$

$$\approx -|\nabla \Phi|^2 \psi_0 \quad \text{by dropping } \nabla A \text{ terms and imaginary terms}$$

$$\Rightarrow -|\nabla \Phi|^2 \psi_0 + \frac{\omega^2}{c^2} \psi_0$$

$$\Rightarrow |\nabla \Phi|^2 = \frac{\omega^2}{c^2} = \frac{\omega^2}{c_0^2} n^2(x)$$

Define  $\underline{k} = \nabla \Phi$

We have  $\psi = A e^{i \left[ \int \underline{k} \cdot d\underline{x} - \omega dt \right]} = A e^{i \Phi_{\text{total}}(x,t)}$

So the incremental total phase,

$$d\Phi = \underline{k} \cdot d\underline{x} - \omega dt$$

$$4a) \text{ Part d: } \Phi_{tot} = \int_a^b [k \cdot dx - \omega dt]$$

$$\text{As } \omega = \omega(k, x),$$

$$\delta \Phi = \int_a^b [\delta k \cdot dx + k \cdot \delta x - (\frac{\partial \omega}{\partial k} \cdot \delta k + \frac{\partial \omega}{\partial x} \cdot \delta x) dt] = 0$$

$$\text{Second term} = \int k \cdot \delta x$$

$$= k \cdot \delta x \Big|_a^b - \int \delta x \cdot \frac{dk}{dx} dx$$

By matching coef. of  $\delta x$  and  $\delta k$  separately, we have

$$\frac{dx}{dt} = \frac{\partial \omega}{\partial k} \quad \text{and} \quad \frac{dk}{dt} = -\frac{\partial \omega}{\partial x} //$$

$$b) \text{ Abbreviated phase } \Phi_0 = \int_a^b k dl$$

$$\delta \Phi_0 = 0 \Rightarrow \delta \int_a^b n dl = 0$$

$$\Rightarrow 0 = \int_a^b \delta n dl + \int_a^b n(x) \delta s dl, \quad \delta n = \frac{\partial n}{\partial x} \cdot \delta x$$

For 2<sup>nd</sup> term, we want  $\delta x$ :

$$\text{Consider } dl^2 = dx \cdot dx$$

$$dl \delta dl = dl \delta s dl = dx \cdot \delta s x$$

$$\Rightarrow \delta s dl = \frac{dx}{dl} \delta s x$$

$$\Rightarrow \int_a^b n(x) \delta s dl = \int_a^b n(x) \frac{dx}{dl} \cdot \delta s x$$

$$= - \int_a^b \frac{d}{dl} \left[ n(x) \frac{dx}{dl} \right] \cdot \delta x dl$$

\*b) Cont'd :

$$\text{By match } S_{\underline{x}} dl: \quad \frac{\partial n(\underline{x})}{\partial \underline{x}} = \frac{d}{dl} \left[ n(\underline{x}) \frac{d\underline{x}}{dl} \right]$$

Difference from a) :

Eq. b) doesn't involve frequency or time. So there is no information on how the wave propagates as time goes.

$$c) \quad \frac{\partial n}{\partial \underline{x}} = \frac{d}{dl} \left[ n(\underline{x}) \frac{d\underline{x}}{dl} \right] \Rightarrow \nabla n = \left( \nabla n \cdot \frac{d\underline{x}}{dl} \right) \frac{d\underline{x}}{dl} + n(\underline{x}) \frac{d^2 \underline{x}}{dl^2}$$

By identifying tangent vector  $\frac{d\underline{x}}{dl} = \underline{\hat{t}}$  and  $\frac{1}{R} = \frac{d^2 \underline{x}}{dl^2}$

with  $R$  being radius of curvature,

$$\Rightarrow \frac{1}{R} = \frac{1}{n(\underline{x})} \left[ \nabla n - (\nabla n \cdot \underline{\hat{t}}) \underline{\hat{t}} \right]$$

$\uparrow$   
 $\nabla n \cdot \hat{n}$  where  $\hat{n} \equiv$  unit normal vector to path.

$$5.a) \quad \nabla^2 \psi + \frac{\omega^2}{c_0^2} n^2(\underline{x}) \psi = 0$$

For  $n^2(\underline{x}) = 1 + S(\underline{x})$  and assuming the sound beamed in  $\hat{z}$  direction, we can write

$$\psi \approx \psi_0 e^{ik_z z} \quad \text{where} \quad \left| \frac{\partial_z \psi_0}{\psi_0} \right| \ll |k_z|$$

$$\text{So } \nabla \psi = (\nabla \psi_0 + ik_z \hat{z} \psi_0) e^{ik_z z}$$

$$\begin{aligned} \nabla^2 \psi = \nabla \cdot \nabla \psi &= (\nabla^2 \psi_0 + ik_z \hat{z} \nabla \psi_0) e^{ik_z z} + ik_z \hat{z} e^{ik_z z} \cdot (\nabla \psi_0 + ik_z \psi_0 \hat{z}) \\ &= [\nabla^2 \psi_0 + 2ik_z \partial_z \psi_0 - k_z^2 \psi_0] e^{ik_z z} \\ &\approx \left[ \nabla_{\perp}^2 + 2ik_z \partial_z - k_z^2 \right] \psi_0 e^{ik_z z} \quad \text{by } |k_z| \gg \left| \frac{\partial_z \psi_0}{\psi_0} \right| \end{aligned}$$

Recall for zeroth order:  $k_z^2 = \frac{\omega^2}{c_0^2}$

$$\Rightarrow 2ik_z \partial_z \psi_0 + \nabla_{\perp}^2 \psi_0 + \frac{\omega^2}{c_0^2} S(\underline{x}) \psi_0 = 0 //$$

b)  $k_z$  is defined as  $\frac{1}{\psi} \frac{\partial \psi}{\partial z}$

i) Approximation:  $|k_z| \gg \left| \frac{\partial_z \psi_0}{\psi_0} \right|$

change in phase  $\gg$  that of amp. in  $z$ -direction.

ii) The  $S(\underline{x})$  term corresponds to the spread in  $\perp$  direction (i.e.  $\nabla_{\perp}^2 \psi$ ) and the change in amplitude in  $z$  direction (i.e.  $\partial_z \psi_0$ )

iii)  $\partial_z \psi$ ,  $S(\underline{x}) \psi$  should be in same order

$$5. c) \text{ let } \psi = A(\underline{x}) e^{i\phi(\underline{x})}$$

$$\partial_z \psi = [\partial_z A + i(\partial_z \phi) A] e^{i\phi}$$

$$\nabla_{\perp} \psi = [\nabla_{\perp} A + i(\nabla_{\perp} \phi) A] e^{i\phi}$$

$$\nabla_{\perp}^2 \psi = \nabla_{\perp} \cdot \nabla_{\perp} \psi = [\nabla_{\perp}^2 A + i \nabla_{\perp} \phi \cdot \nabla_{\perp} A + i A (\nabla_{\perp}^2 \phi)] e^{i\phi} \\ + [\nabla_{\perp} A + i(\nabla_{\perp} \phi) A] \cdot i \nabla_{\perp} \phi e^{i\phi}$$

$$= \nabla_{\perp}^2 A + 2i(\nabla_{\perp} \phi)(\nabla_{\perp} A) + i A (\nabla_{\perp}^2 \phi) - |\nabla_{\perp} \phi|^2 A$$

$$\Rightarrow 2ik_z \partial_z A - 2k_z (\partial_z \phi) A + \nabla_{\perp}^2 A + 2i(\nabla_{\perp} \phi) \cdot (\nabla_{\perp} A)$$

$$+ i A (\nabla_{\perp}^2 \phi) - |\nabla_{\perp} \phi|^2 A + \frac{\omega^2}{c_0^2} S(\underline{x}) A = 0$$

Real Part:

$$- 2k_z (\partial_z \phi) A + \nabla_{\perp}^2 A - |\nabla_{\perp} \phi|^2 A + \frac{\omega^2}{c_0^2} S(\underline{x}) A = 0$$

Except for the 2<sup>nd</sup> term,  $S(\underline{x})$  gives rise to change in  $\phi$  as in eikonal theory:  $|\nabla \phi|^2 = \frac{\omega^2}{c_0^2} n^2(\underline{x})$

Imaginary Part:

$$2k_z \partial_z A + 2(\nabla_{\perp} \phi) \cdot (\nabla_{\perp} A) + A (\nabla_{\perp}^2 \phi) = 0$$



6) Hamiltonian for 3D SHO:

$$H = \frac{1}{2m} [ p_1^2 + p_2^2 + p_3^2 + m^2 \omega_1^2 q_1^2 + m^2 \omega_2^2 q_2^2 + m^2 \omega_3^2 q_3^2 ]$$

where  $\omega_i^2 = k_i/m$        $q_1, q_2, q_3 \Leftrightarrow x, y, z$

To get Hamilton-Jacobi Eq, we first let  $p_i = \frac{\partial S}{\partial q_i}$

$$\Rightarrow \frac{\partial S}{\partial t} + H(q_i, \frac{\partial S}{\partial q_i}) = 0$$

$$= \frac{\partial S}{\partial t} + \frac{1}{2m} \left[ \left( \frac{\partial S}{\partial q_1} \right)^2 + \left( \frac{\partial S}{\partial q_2} \right)^2 + \left( \frac{\partial S}{\partial q_3} \right)^2 + m^2 \omega_1^2 q_1^2 + m^2 \omega_2^2 q_2^2 + m^2 \omega_3^2 q_3^2 \right]$$

No explicit time-dependence on  $S$ , except  $\frac{\partial S}{\partial t}$

$$\Rightarrow S = S_0(q_i) - Et \quad \left( \text{OR } S = W - Et \right)$$

$\Rightarrow H = E$

We can see both  $H$  and  $S_0$  are separable:

$$H = \sum_i \frac{1}{2m} \left[ \left( \frac{\partial S_i}{\partial q_i} \right)^2 + m^2 \omega_i^2 q_i^2 \right], \quad S_0 = \sum_i S_i(q_i)$$

So, we need to solve

$$\left( \frac{\partial S_i}{\partial q_i} \right)^2 + m^2 \omega_i^2 q_i^2 = 2mE_i$$

each  $[ ]$  is function of  $q_i$  only

for  $i=1, 2, 3$ . Also  $E = E_1 + E_2 + E_3$

$$S_i(q_i) = \sqrt{2mE_i} \int dq_i \sqrt{1 - \frac{m\omega_i^2 q_i^2}{2E_i}} = S_i(q_i; E_i)$$

b) Cont'd,

$$\text{Note } S = S_1(q_1) + S_2(q_2) + S_3(q_3) - Et$$

To get  $q_i(t)$ , we take

$$Q_i = \beta_i = \frac{\partial S}{\partial E_i} = \frac{\partial S_i}{\partial E_i} - t$$

$$\Rightarrow t + \beta_i = \frac{\partial}{\partial E_i} \int dq_i \sqrt{2mE_i - m^2\omega_i^2 q_i^2}$$

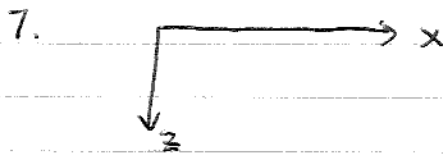
$$= \sqrt{\frac{m}{2E_i}} \int dq_i \frac{1}{\sqrt{1 - \frac{m\omega_i^2 q_i^2}{2E_i}}} = \frac{1}{\omega_i} \sin^{-1} \left( q_i \sqrt{\frac{m\omega_i^2}{2E_i}} \right)$$

$$\Rightarrow \left\{ \begin{array}{l} q_i(t) = \sqrt{\frac{2E_i}{m\omega_i^2}} \sin[\omega_i(t + \beta_i)] \end{array} \right.$$

for  $i = 1, 2, 3$

$$\left\{ \begin{array}{l} p_i(t) = \frac{\partial S}{\partial q_i} = \frac{\partial S_i}{\partial q_i} = \sqrt{2mE_i - m^2\omega_i^2 q_i^2} \end{array} \right.$$

$$= \sqrt{2mE_i} \sqrt{1 - \frac{m\omega_i^2 q_i^2}{2E_i}} = \sqrt{2mE_i} \cos[\omega_i(t + \beta_i)]$$



By Fermat's Principle, we want  $ST = S \int dt = 0$

$$dt = \frac{dl}{c(z)} \quad \text{with } dl = \sqrt{dx^2 + dz^2}$$

$$= \sqrt{\left(\frac{dx}{dz}\right)^2 + 1} dz$$

$$\Rightarrow ST = S \int \frac{1}{c(z)} \sqrt{(x')^2 + 1} dz \quad x' = \frac{dx}{dz}$$

As  $\frac{\partial}{\partial x}$  (integrand) = 0,

$$\Rightarrow \frac{d}{dz} \frac{\partial}{\partial x'} \left[ \frac{1}{c(z)} \sqrt{(x')^2 + 1} \right] = 0$$

$$\Rightarrow \frac{1}{c(z)} \frac{x'}{\sqrt{(x')^2 + 1}} = \text{const.} = \frac{1}{c_0} \quad \text{where } c(z) < c_0 [= c(z_0)]$$

$$\Rightarrow \frac{dx}{dz} = \pm \frac{c/c_0}{\sqrt{1 - c^2/c_0^2}} \quad \text{OR} \quad \frac{dz}{dx} = \pm \frac{\sqrt{1 - c^2/c_0^2}}{c/c_0}$$

$$\Rightarrow x(z) = \pm \int \frac{c(z)}{\sqrt{c_0^2 - c(z)^2}} dz$$

$$\Downarrow$$

$$\frac{dz}{dx} = 0 \quad \text{at } z = z_0, c = c_0$$