

Principle of Maximum  
Likelihood,  
Propagation of Uncertainties for  
Racket Balls and Rods

Lecture # 5  
Physics 2BL  
Spring 2012

# Outline

- Review of Gaussian distributions and rejection of data?
- Uncertainties for lab 2
  - Propagate errors
  - Minimize errors

# Schedule

Meeting	Experiment
1 (Apr 2-6)	None (start Taylor)
2 (Apr 9-13)	1
3 (Apr 16-20)	1
4 (Apr 23-27)	2
5 (Apr 30-May4)	2
6 (May 7-11)	3
7 (May 14-18)	3
8 (May 21-25)	4
9 (May 28-June 1)	4
10 (June 4-8)	FINAL

# Clicker Question 6

What is the correct way to report  $653 \pm 55.4$  m

- (a)  $653.0 \pm 55.4$  m
- (b)  $653 \pm 55$  m
- (c)  $650 \pm 55$  m
- (d)  $650 \pm 60$  m

Keep one significant figure

Last sig fig of answer should be same order of magnitude as error

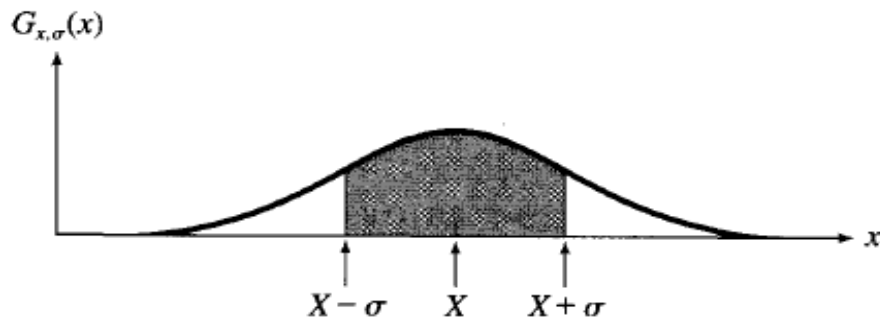
## The Gauss, or Normal Distribution

normalize  $e^{-(x-X)^2/2\sigma^2} \longrightarrow \int_{-\infty}^{+\infty} f(x)dx = 1$

↓

$$G_{X,\sigma}(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-(x-X)^2/2\sigma^2}$$

standard deviation  $\sigma_x =$  width parameter of the Gauss function  $\sigma$   
 the mean value of  $x =$  true value  $X$



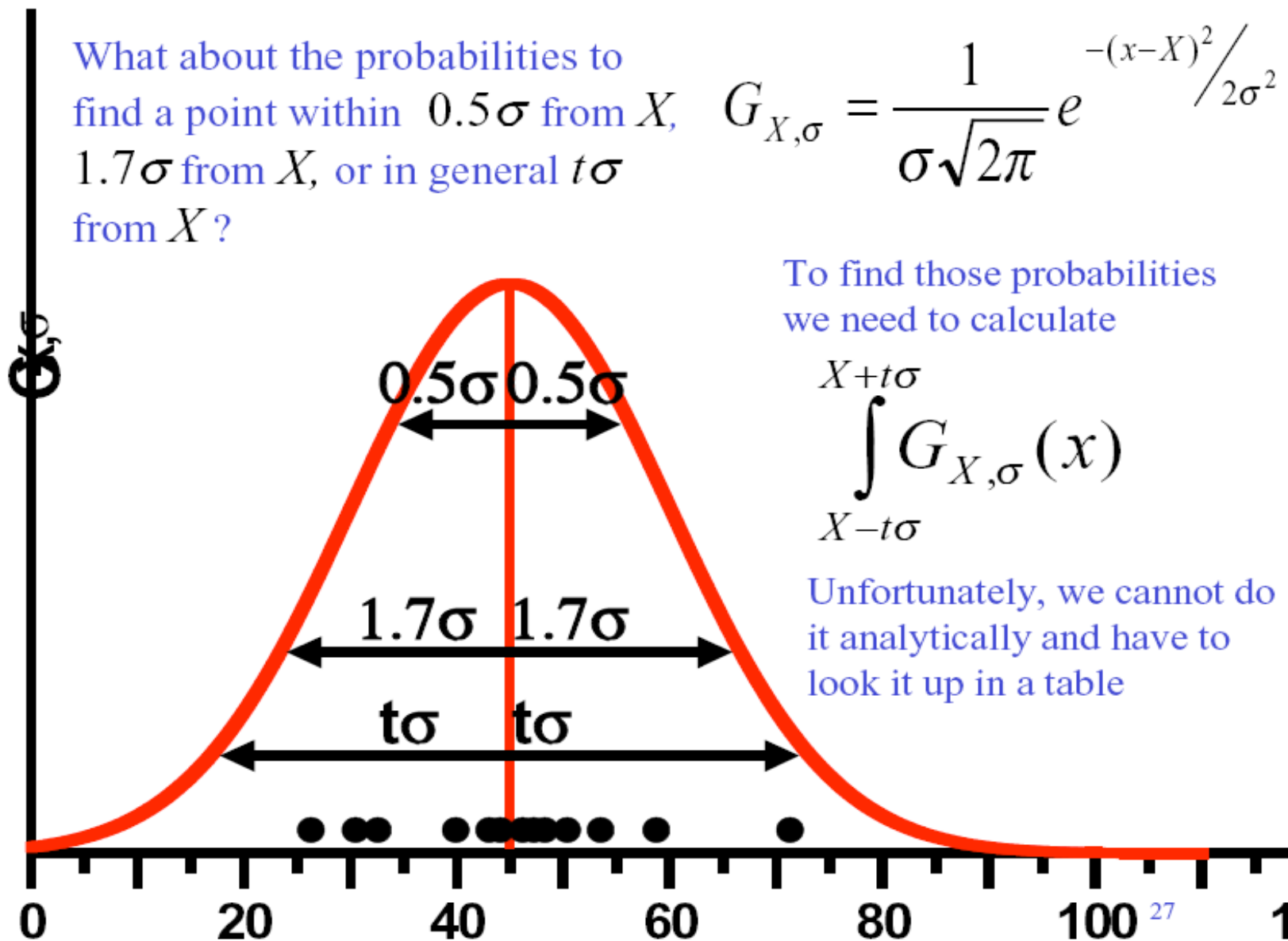
What about the probabilities to find a point within  $0.5\sigma$  from  $X$ ,  $1.7\sigma$  from  $X$ , or in general  $t\sigma$  from  $X$ ?

$$G_{X,\sigma} = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-X)^2}{2\sigma^2}}$$

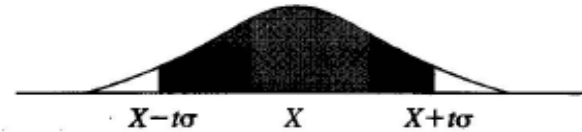
To find those probabilities we need to calculate

$$\int_{X-t\sigma}^{X+t\sigma} G_{X,\sigma}(x)$$

Unfortunately, we cannot do it analytically and have to look it up in a table



**Table A.** The percentage probability,  
 $Prob(\text{within } t\sigma) = \int_{X-t\sigma}^{X+t\sigma} G_{X,\sigma}(x) dx,$   
as a function of  $t$ .



$t$	0.00	0.01	0.02	0.03	0.04	0.05	0.06	0.07	0.08	0.09
0.0	0.00	0.80	1.60	2.39	3.19	3.99	4.78	5.58	6.38	7.17
0.1	7.97	8.76	9.55	10.34	11.13	11.92	12.71	13.50	14.28	15.07
0.2	15.85	16.63	17.41	18.19	18.97	19.74	20.51	21.28	22.05	22.82
0.3	23.58	24.34	25.10	25.86	26.61	27.37	28.12	28.86	29.61	30.35
0.4	31.08	31.82	32.55	33.28	34.01	34.73	35.45	36.16	36.88	37.59
0.5	38.29	38.99	39.69	40.39	41.08	41.77	42.45	43.13	43.81	44.48
0.6	45.15	45.81	46.47	47.13	47.78	48.43	49.07	49.71	50.35	50.98
0.7	51.61	52.23	52.85	53.46	54.07	54.67	55.27	55.87	56.46	57.05
0.8	57.63	58.21	58.78	59.35	59.91	60.47	61.02	61.57	62.11	62.65
0.9	63.19	63.72	64.24	64.76	65.28	65.79	66.29	66.80	67.29	67.78
1.0	68.27	68.75	69.23	69.70	70.17	70.63	71.09	71.54	71.99	72.43
1.1	72.87	73.30	73.73	74.15	74.57	74.99	75.40	75.80	76.20	76.60
1.2	76.99	77.37	77.75	78.13	78.50	78.87	79.23	79.59	79.95	80.29
1.3	80.64	80.98	81.32	81.65	81.98	82.30	82.62	82.93	83.24	83.55
1.4	83.85	84.15	84.44	84.73	85.01	85.29	85.57	85.84	86.11	86.38
1.5	86.64	86.90	87.15	87.40	87.64	87.89	88.12	88.36	88.59	88.82
1.6	89.04	89.26	89.48	89.69	89.90	90.11	90.31	90.51	90.70	90.90
1.7	91.09	91.27	91.46	91.64	91.81	91.99	92.16	92.33	92.49	92.65
1.8	92.81	92.97	93.12	93.28	93.42	93.57	93.71	93.85	93.99	94.12
1.9	94.26	94.39	94.51	94.64	94.76	94.88	95.00	95.12	95.23	95.34
2.0	95.45	95.56	95.66	95.76	95.86	95.96	96.06	96.15	96.25	96.34
2.1	96.43	96.51	96.60	96.68	96.76	96.84	96.92	97.00	97.07	97.15
2.2	97.22	97.29	97.36	97.43	97.49	97.56	97.62	97.68	97.74	97.80

$t = 1$

# Change to rubric for Exp 2

Calculate the expected number of trials that should exceed your average time by one standard deviation and compare it to what you observe.



# Clicker Question 7

What is your age?

(a)  $\leq 18$

(b) 19,20

(c) 21,22

(d) 23,24

(e)  $\geq 25$

## Compatibility of a measured result(s): t-score

- Best estimate of  $x$ :

$$x_{best} \pm \sigma_{\bar{X}}$$

- Compare with expected answer  $x_{exp}$  and compute t-score:

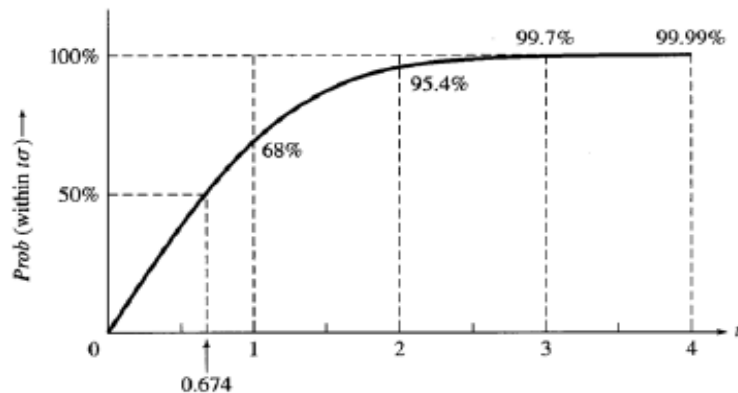
$$t \equiv \frac{|x_{best} - x_{expected}|}{\sigma_X}$$

- This is the number of standard deviations that  $x_{best}$  differs from  $x_{exp}$ .
- Therefore, the probability of obtaining an answer that differs from  $x_{exp}$  by  $t$  or more standard deviations is:

$$\text{Prob(outside } t\sigma) = 1 - \text{Prob(within } t\sigma)$$

# “Acceptability” of a measured result Conventions

- Large probability means likely outcome and hence reasonable discrepancy.
- “reasonable” is a matter of convention...
- We define:



$\text{erf}(t)$  – error function

↓  
< 5 % - significant discrepancy,  $t > 1.96$

< 1 % - highly significant discrepancy,  $t > 2.58$

↑  
boundary for unreasonable improbability

If the discrepancy is beyond the **chosen** boundary for unreasonable improbability,  $\implies$  the theory and the measurement are incompatible (at the stated level)

# Useful concept for complicated formula

- Often the quickest method is to calculate with the extreme values

- $q = q(x)$

- $q_{\max} = q(\bar{x} + \delta x)$

- $q_{\min} = q(\bar{x} - \delta x)$

- $\delta q = (q_{\max} - q_{\min})/2$  (3.39)

# Principle of Maximum Likelihood

- Best estimates of  $X$  and  $\sigma$  from  $N$  measurements  $(x_1 - x_N)$  are those for which  $\text{Prob}_{X,\sigma}(x_i)$  is a maximum

## Clicker Question 8

Upon flipping a coin three times, what are the chances of three heads in a row?

- (a) 1
- (b) 0.5
- (c) 0.25
- (d) 0.125
- (e) 0.0625

# The Principle of Maximum Likelihood

Recall the probability density for measurements of some quantity  $x$  (distributed as a Gaussian with mean  $X$  and standard deviation  $\sigma$ )

$$P_{X,\sigma}(x) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-X)^2}{2\sigma^2}}$$

Normal distribution is one example of  $P(x)$ .

Now, lets make repeated measurements of  $x$  to help reduce our errors.

$$x_1, x_2, x_3, \dots, x_n$$

We define the Likelihood as the product of the probabilities. The larger  $L$ , the more likely a set of measurements is.

$$L = P(x_1)P(x_2)P(x_3)\dots P(x_n)$$

Is  $L$  a Probability?

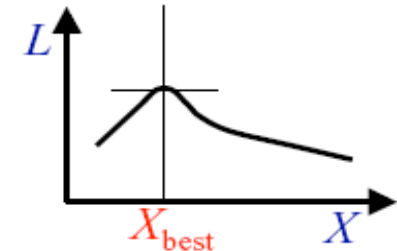
Why does  $\max L$  give the best estimate?

The best estimate for the parameters of  $P(x)$  are those that maximize  $L$ .

# Using the Principle of Maximum Likelihood: Prove the mean is best estimate of $X$

Assume  $X$  is a parameter of  $P(x)$ .

When  $L$  is maximum, we must have:  $\frac{\partial L}{\partial X} = 0$



Lets assume a Normal error distribution and find the formula for the best value for  $X$ .

$$L = P(x_1)P(x_2)\dots P(x_n) = \prod_{i=1}^n P(x_i)$$

$$L = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x_i - X)^2}{2\sigma^2}} = \frac{1}{(2\pi)^{\frac{n}{2}} \sigma^n} e^{-\sum_{i=1}^n \frac{(x_i - X)^2}{2\sigma^2}}$$

$$L = Ce^{-\chi^2/2}$$

$$\chi^2 = \sum_{i=1}^n \frac{(x_i - X)^2}{\sigma^2}$$

Defininition

$$\frac{\partial L}{\partial X} = 0 = Ce^{-\chi^2/2} \frac{-1}{2} \frac{\partial \chi^2}{\partial X}$$

$$\Rightarrow \frac{\partial \chi^2}{\partial X} = 0 \quad \leftarrow$$

$$\frac{\partial \chi^2}{\partial X} = \frac{1}{\sigma^2} \sum_{i=1}^n 2(x_i - X) = 0$$

$$\sum_{i=1}^n (x_i - X) = 0$$

$$\sum_{i=1}^n x_i - nX = 0$$

$$X = \frac{1}{n} \sum_{i=1}^n x_i$$

**Q.E.D.**  
the mean



## What is the Error on the Mean

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$$

Formula for mean of measurements. (We just proved that this is the best estimate of the true  $x$ .)

Now, use propagation of errors to get the error on the mean.

$$\sigma_{\bar{x}} = \frac{\partial \bar{x}}{\partial x_1} \sigma_{x_1} \oplus \frac{\partial \bar{x}}{\partial x_2} \sigma_{x_2} \oplus \dots \oplus \frac{\partial \bar{x}}{\partial x_n} \sigma_{x_n}$$

$$\frac{\partial \bar{x}}{\partial x_i} = \frac{1}{n}$$

$$\sigma_{\bar{x}} = \sqrt{\sum_{i=1}^n \left( \frac{\sigma_{x_i}}{n} \right)^2} = \sqrt{n \left( \frac{\sigma}{n} \right)^2} = \frac{\sigma}{\sqrt{n}}$$

**What would you do if the  $x_i$  had different errors?**

We got the error on the mean (SDOM) by propagating errors.

# The Four Experiments

- **Determine the average density of the earth**  
**Weigh the Earth, Measure its volume**
  - Measure simple things like lengths and times
  - Learn to estimate and propagate errors
- **Non-Destructive measurements of densities, inner structure of objects**
  - Absolute measurements *vs.* Measurements of variability
  - Measure moments of inertia
  - Use repeated measurements to reduce random errors
- **Construct and tune a shock absorber**
  - Adjust performance of a mechanical system
  - Demonstrate critical damping of your shock absorber
- **Measure coulomb force and calibrate a voltmeter.**
  - Reduce systematic errors in a precise measurement.

# Rotational Kinematics

## Linear Kinematics

$$v_f = v_i + a\Delta t$$

$$\Delta s = v_i\Delta t + \frac{1}{2}a(\Delta t)^2$$

$$v_f^2 = v_i^2 + 2a\Delta s$$

## Rotational Kinematics

$$\omega_f = \omega_i + \alpha\Delta t$$

$$\Delta\theta = \omega_i\Delta t + \frac{1}{2}\alpha(\Delta t)^2$$

$$\omega_f^2 = \omega_i^2 + 2\alpha\Delta\theta$$

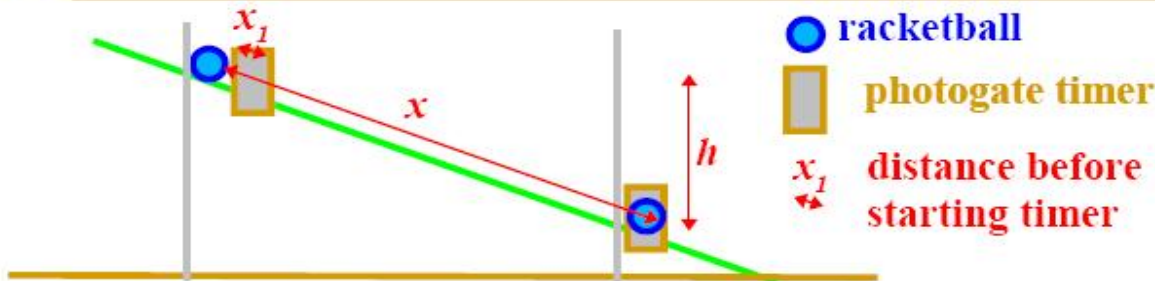
$$s = \theta r \quad v = \omega r \quad a_t = \alpha r$$

# Racquet Balls



We should check if the variation in  $d$  is much less than 10%.

# Measuring $I$ by Rolling Objects



1. Measure  $M$  and  $R$
2. Using photo gate timer measure the time,  $t$ , to travel distance  $x$

$$Mgh = \frac{1}{2} Mv^2 + \frac{1}{2} I\omega^2$$

energy conservation

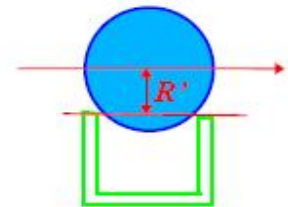
$$v = R'\omega$$

rolling radius

$$v = \frac{2x}{t}$$

for uniform acceleration

rolling radius  $R'$



$$Mgh = \frac{1}{2} v^2 \left( M + \frac{I}{R'^2} \right)$$

$$gh = \frac{2x^2}{t^2} \left( 1 + \frac{I}{MR'^2} \right)$$

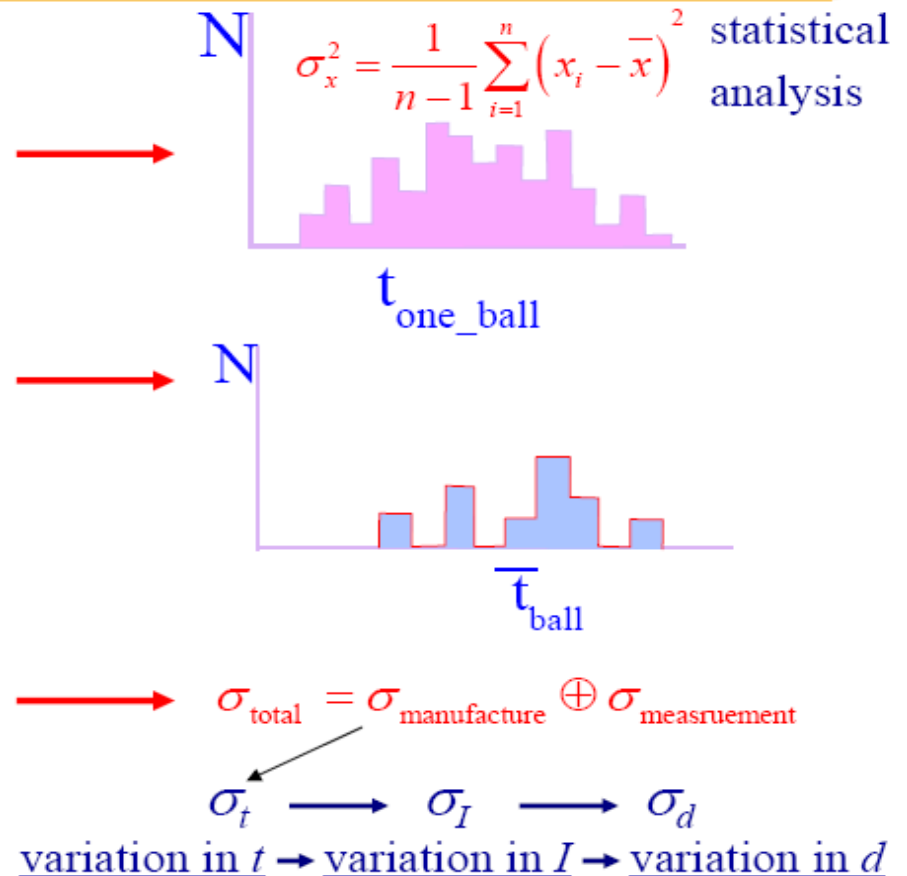
$$\frac{I}{MR'^2} = \left( \frac{ght^2}{2x^2} - 1 \right)$$

$$\tilde{I} \equiv \frac{I}{MR^2} = \frac{R'^2}{R^2} \left( \frac{ght^2}{2x^2} - 1 \right)$$

# Measuring the Variation in Thickness of the Shell



- 1. Measure rolling time of one ball many times to determine the measurement error in  $t$ ,  $\sigma_{\text{measurement}}$
- 2. Measure rolling time of many balls to determine the total spread in  $t$ ,  $\sigma_{\text{total}}$
- 3. Calculate the spread in time due to ball manufacture,  $\sigma_{\text{manufacture}}$ , by subtracting the measurement error
- 4. Propagate error on  $t$  into error on  $I$  and then into error on thickness  $d$



# Propagate Error from $I$ to $d$



$$I = \frac{2}{5} M \frac{R^5 - r^5}{R^3 - r^3}$$

measured thickness and  
radius for one ball

$$z \equiv \frac{r}{R} \approx \frac{28.25 - 4.5 \text{ mm}}{28.25 \text{ mm}} \approx 0.841$$

$d=4.5 \text{ mm}$   $R=28.25 \text{ mm}$   
 $d=R-r$

$$\tilde{I}(0.841) \equiv \frac{I}{MR^2} = \frac{2}{5} \frac{1-z^5}{1-z^3} \approx 0.571892$$

$$\tilde{I}(0.840) \equiv \frac{I}{MR^2} = \frac{2}{5} \frac{1-z^5}{1-z^3} \approx 0.571366$$

←  $\delta z \leftrightarrow \delta I$  numerically

$$\frac{\partial z}{\partial \tilde{I}} = \frac{0.841 - 0.840}{0.571892 - 0.571366} = \frac{0.001}{0.00526} = 1.901$$

$$\frac{\sigma_d}{d} = \frac{\sigma_r}{d} = \frac{R\sigma_z}{d} = \frac{R\tilde{I}}{d} \frac{\partial z}{\partial \tilde{I}} \frac{\sigma_{\tilde{I}}}{\tilde{I}} \approx \frac{(28.25 \text{ mm})(0.572)}{4.5 \text{ mm}} (1.901) \frac{\sigma_{\tilde{I}}}{\tilde{I}} = 6.826 \frac{\sigma_{\tilde{I}}}{\tilde{I}} \approx 6.8 \frac{\sigma_{\tilde{I}}}{\tilde{I}}$$

$$\frac{\sigma_d}{d} \approx 6.8 \frac{\sigma_{\tilde{I}}}{\tilde{I}}$$

# Propagate Error from $t$ to $I$



$$\tilde{I} = \frac{I}{MR^2} = \frac{R'^2}{R^2} \left( \frac{ght^2}{2x^2} - 1 \right) \approx 0.572 \quad \text{from previous page}$$

$$\frac{\partial \tilde{I}}{\partial t} = \frac{R'^2}{R^2} \left( \frac{ght}{x^2} \right) \quad \text{compute derivative}$$

$$\sigma_{\tilde{I}} = \frac{R'^2}{R^2} \left( \frac{ght}{x^2} \right) \sigma_t \quad \text{propagate error}$$

$$\frac{\sigma_{\tilde{I}}}{\tilde{I}} \approx 4 \frac{\sigma_t}{t}$$

$$\frac{\sigma_{\tilde{I}}}{\tilde{I}} = \frac{\left( \frac{ght}{x^2} \right)}{\left( \frac{ght^2}{2x^2} - 1 \right)} \sigma_t \approx \frac{\left( \frac{ght}{x^2} \right)}{\frac{R^2}{R'^2} (0.572)} \sigma_t \quad \text{work out fractional error numerically}$$

$$\frac{\sigma_d}{d} \approx 6.8 \frac{\sigma_{\tilde{I}}}{\tilde{I}} \approx 27 \frac{\sigma_t}{t}$$

$$\left( \frac{ght}{x^2} \right) = \frac{2}{t} \left( \frac{R^2}{R'^2} \tilde{I} + 1 \right)$$

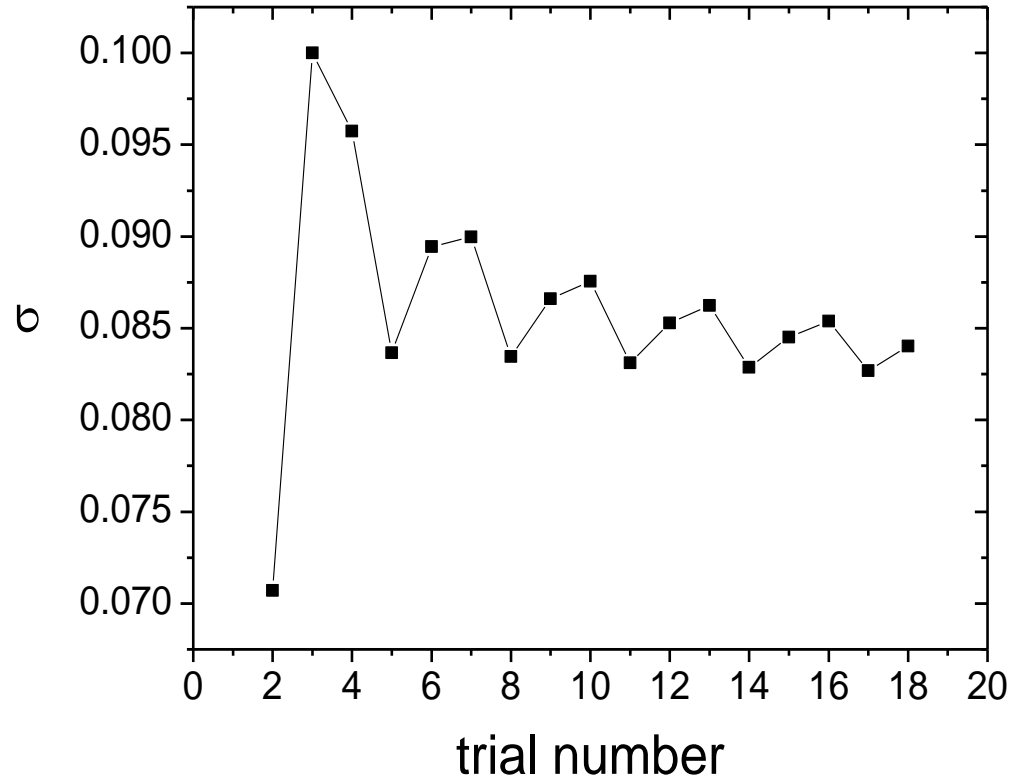
$$\frac{\sigma_{\tilde{I}}}{\tilde{I}} \approx \frac{\frac{2}{t} \left( \frac{R^2}{R'^2} \tilde{I} + 1 \right)}{\frac{R^2}{R'^2} (0.572)} \sigma_t = \frac{2 \left( 0.572 + \frac{R'^2}{R^2} \right)}{(0.572)} \frac{\sigma_t}{t} \approx 4 \frac{\sigma_t}{t}$$

to get a 10% error on the thickness  
we need 0.37% error on the rolling time

accuracy can be improved by rolling  
each ball many times



# Standard Deviation versus Trial Number



=STDEV(A\$1:A2)

# Remember

- Finish experiment #2
- Homework Taylor #8.6, 8.10
- Read Taylor through Chapter 9