

## Physics 110A: Midterm Exam #2

Instructions: Do either problem. Do only one problem.

[1] A point particle of mass  $m$  slides frictionlessly under the influence of gravity along a parabola. The parabola is defined by the equation  $y = x^2/2b$ , where  $b$  is a constant.

(a) Treat the confinement of the particle to the parabola as a constraint. Using generalized coordinates  $x$  and  $y$ , find the Lagrangian  $L$ .

(b) Find the equations of motion.

(c) Identify all conserved quantities.

(d) Assuming that the particle is released from rest at a location  $x = x_0$ , derive expressions for the forces of constraint  $Q_x$  and  $Q_y$  as a function of the horizontal coordinate  $x$  alone.

(e) Suppose that the mass  $m$  serves as the point of support of a pendulum bob of mass  $\mu$ , suspended via a massless rigid rod of length  $\ell$ . The pendulum is free to swing in the  $(x, y)$  plane. *Implementing the constraint  $y = x^2/2b$  at the outset*, derive the Lagrangian  $L(x, \theta, \dot{x}, \dot{\theta})$ .

(f) Find expressions for the momenta  $p_x$  and  $p_\theta$ .

[2] A pendulum consisting of a massless rigid rod of length  $\ell$  and a point mass  $m$  is suspended from a hoop of radius  $a$  which lies in a horizontal plane. The point of suspension is driven to move around the hoop with constant angular velocity  $\Omega$ . The pendulum's instantaneous motion is constrained to lie in a vertical plane bisecting the hoop. *Do not* use the method of undetermined multipliers. (Since the constraint is "holonomic" it may be implemented at the outset.)

(a) Using the single generalized coordinate  $\theta$ , the instantaneous displacement of the pendulum rod from the vertical, write down the Lagrangian for the system.

(b) What is the Hamiltonian? Is  $H$  conserved? Explain why or why not.

(c) Write down the equations of motion.

(d) Show that the equations of motion may be written in the form  $\ddot{\theta} = -\partial W_{\text{eff}}/\partial\theta$ . Find the (scaled) effective potential,  $W_{\text{eff}}(\theta)$ .

(e) Derive an equation for the equilibrium value of  $\theta_0$ , *i.e.* the value of  $\theta$  for which the generalized force  $F_\theta$  vanishes.

(f) Suppose  $a = \ell/\sqrt{2}$  and furthermore that  $\theta_0 = \frac{1}{4}\pi$ . Solve then for  $\Omega$  and for the frequency of small oscillations about equilibrium.

## SOLUTIONS

$$[1] \quad \left. \begin{aligned} (a) \quad T &= \frac{1}{2} m(\dot{x}^2 + \dot{y}^2) \\ U &= mgy \end{aligned} \right\} \quad L = \frac{1}{2} m(\dot{x}^2 + \dot{y}^2) - mgy$$

(b) Constraint:

$$G(x, y) = y - \frac{x^2}{2b} = 0$$

Thus,

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_\sigma} \right) - \frac{\partial L}{\partial q_\sigma} = \sum_{j=1}^k \lambda_j \frac{\partial G_j}{\partial q_\sigma} \quad (k=1, \text{ here}; \sigma=1(x), 2(y))$$

$$(1) \quad m\ddot{x} = -\lambda \frac{x}{b} = Q_x$$

$$(2) \quad m\ddot{y} + mg = \lambda = Q_y$$

$$(3) \quad y - \frac{x^2}{2b} = 0 \quad (\text{constraint})$$

$$(c) \quad H = E = x p_x + y p_y - L = \frac{1}{2} m(\dot{x}^2 + \dot{y}^2) + mgy \quad \text{conserved}$$

$$(d) \quad \text{Substitute for } y: \quad y = \frac{x^2}{2b} \Rightarrow \dot{y} = \frac{x}{b} \dot{x}$$

$$\rightarrow E = \frac{1}{2} m \left( 1 + \frac{x^2}{b^2} \right) \dot{x}^2 + mg \frac{x^2}{2b} = mg \frac{x_0^2}{2b}$$

Hence,

$$\dot{x}^2 = gb \frac{x_0^2 - x^2}{b^2 + x^2}$$

We also need

$$\ddot{y} = \frac{x}{b} \ddot{x} + \frac{1}{b} \dot{x}^2$$

Hence from (2)

$$\lambda = m\ddot{y} + mg = m \left( g + \frac{1}{b} x \ddot{x} + \frac{1}{b} \dot{x}^2 \right)$$

and substituting into (1),

$$m\ddot{x} = -\frac{mx}{b} \left( g + \frac{1}{b} x \ddot{x} + \frac{1}{b} \dot{x}^2 \right)$$

Subtracting, we obtain

$$m \frac{\dot{x}^2}{b} + mg = \lambda \left(1 + \frac{x^2}{b^2}\right)$$

$$\Rightarrow \lambda = m \frac{g + \frac{\dot{x}^2}{b}}{1 + \frac{x^2}{b^2}}$$

So we need  $\dot{x}$  as a function of  $x$ . Get this from energy conservation:

$$E = \frac{1}{2} m \left(1 + \frac{x^2}{b^2}\right) \dot{x}^2 + mg \frac{x^2}{2b} = mg \frac{x_0^2}{2b}$$

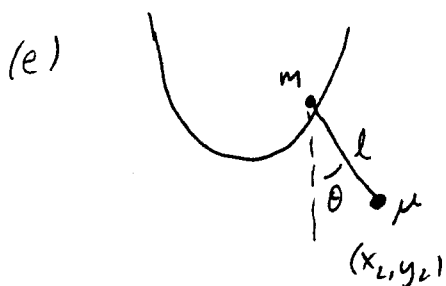
$$\Rightarrow \dot{x}^2 = gb \frac{x_0^2 - x^2}{b^2 + x^2}$$

Thus,

$$Q_y = \lambda = mg \frac{1 + \frac{x_0^2 - x^2}{b^2 + x^2}}{1 + \frac{x^2}{b^2}} = mg b^2 \frac{b^2 + x_0^2}{(b^2 + x^2)^2}$$

$$Q_x = -\frac{x}{b} \lambda = -mg b x \cdot \frac{b^2 + x_0^2}{(b^2 + x^2)^2}$$

Note  $Q_y > 0$ ,  $Q_x > 0$  if  $x < 0$ ,  $Q_x < 0$  if  $x > 0$ , as expected.



$$x_2 = x + l \sin \theta$$

$$y_2 = y - l \cos \theta$$

$$y = \frac{x^2}{2b}$$

$$\dot{x}_2 = \dot{x} + l \cos \theta \dot{\theta}$$

$$\dot{y}_2 = \dot{y} + l \sin \theta \dot{\theta} = \frac{x}{b} \dot{x} + l \sin \theta \dot{\theta}$$

$$\begin{aligned} T &= \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) + \frac{1}{2} \mu (\dot{x}_2^2 + \dot{y}_2^2) \\ &= \frac{1}{2} m \left(1 + \frac{x^2}{b^2}\right) \dot{x}^2 + \frac{1}{2} \mu \left(1 + \frac{x^2}{b^2}\right) \dot{x}^2 + \frac{1}{2} \mu l^2 \dot{\theta}^2 \\ &\quad + \mu l \dot{x} \dot{\theta} \left(\cos \theta + \frac{x}{b} \sin \theta\right) \end{aligned}$$

$$U = mgy + \mu g y_2$$

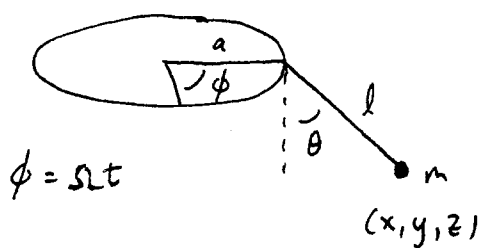
$$= mg \frac{x^2}{2b} + \mu g \left(\frac{x^2}{2b} - l \cos \theta\right)$$

$$\begin{aligned} L &= \frac{1}{2} (m + \mu) \left(1 + \frac{x^2}{b^2}\right) \dot{x}^2 + \frac{1}{2} \mu l^2 \dot{\theta}^2 + \mu l \left(\cos \theta + \frac{x}{b} \sin \theta\right) \dot{x} \dot{\theta} \\ &\quad - (m + \mu) g \frac{x^2}{2b} + \mu g l \cos \theta \end{aligned}$$

$$(f) \quad p_x = \frac{\partial L}{\partial \dot{x}} = (m + \mu) \left(1 + \frac{x^2}{b^2}\right) \dot{x} + \mu l \left(\cos \theta + \frac{x}{b} \sin \theta\right) \dot{\theta}$$

$$p_\theta = \frac{\partial L}{\partial \dot{\theta}} = \mu l^2 \dot{\theta} + \mu l \left(\cos \theta + \frac{x}{b} \sin \theta\right) \dot{x}$$

[2]



$$\begin{cases} x = (a + l \sin \theta) \cos \phi \\ y = (a + l \sin \theta) \sin \phi \\ z = -l \cos \theta \end{cases}$$

$$\dot{x} = -(a + l \sin \theta) \sin \phi \dot{\phi} + l \cos \theta \cos \phi \dot{\theta}$$

$$\dot{y} = (a + l \sin \theta) \cos \phi \dot{\phi} + l \cos \theta \sin \phi \dot{\theta}$$

$$\dot{z} = l \sin \theta \dot{\theta}$$

$$T = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2 + \dot{z}^2) = \frac{1}{2} m (l^2 \dot{\theta}^2 + (a + l \sin \theta)^2 \dot{\phi}^2)$$

$$U = mgz$$

$$L = \frac{1}{2} m l^2 \dot{\theta}^2 + \frac{1}{2} m \Omega^2 (a + l \sin \theta)^2 + mgl \cos \theta$$

$$(b) H = \dot{\theta} p_{\theta} - L \quad ; \quad p_{\theta} = \frac{\partial L}{\partial \dot{\theta}} = m l^2 \dot{\theta}'$$

$$= \frac{1}{2} m l^2 \dot{\theta}^2 - \frac{1}{2} m \Omega^2 (a + l \sin \theta)^2 - mgl \cos \theta$$

$$= \frac{p_{\theta}^2}{2m l^2} - \frac{1}{2} m \Omega^2 (a + l \sin \theta)^2 - mgl \cos \theta$$

$H$  is conserved since  $-\frac{\partial L}{\partial t} = \frac{dH}{dt} = 0$ . But  $H \neq T + U$ !

$$(c) \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0 \quad ;$$

$$m l^2 \ddot{\theta} = -mgl \sin \theta + m \Omega^2 l (a + l \sin \theta) \cos \theta$$

$$(d) \quad \ddot{\theta} = -\frac{g}{l} \sin \theta + \Omega^2 \left( \frac{a}{l} + \sin \theta \right) \cos \theta$$

$$= -\frac{\partial W_{\text{eff}}}{\partial \theta}$$

$$W_{\text{eff}}(\theta) = -\frac{g}{l} \cos \theta + \frac{1}{2} \Omega^2 \left( \frac{a}{l} + \sin \theta \right)^2$$

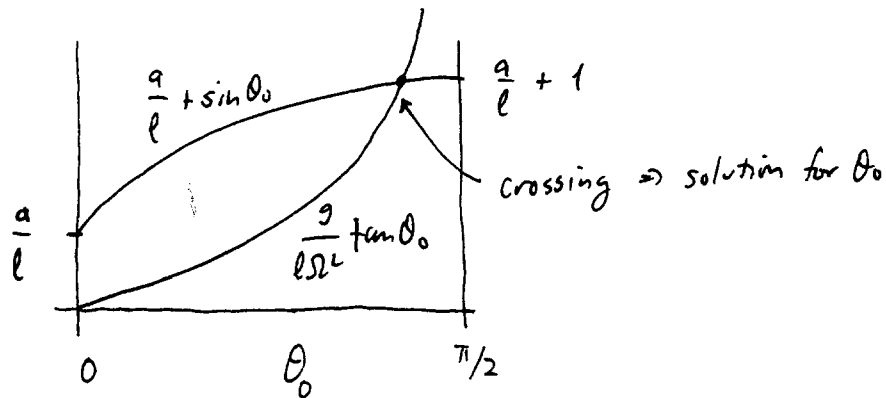
(e) Equilibrium  $\Rightarrow \ddot{\theta} = 0 \Rightarrow \left. \frac{\partial W_{\text{eff}}}{\partial \theta} \right|_{\theta_0} = 0 :$

$$\Omega^2 \left( \frac{a}{l} + \sin \theta_0 \right) \cos \theta_0 = \omega_0^2 \sin \theta_0$$

where  $\omega_0 = \sqrt{\frac{g}{l}}$ . This can also be written

$$\frac{a}{l} + \sin \theta_0 = \frac{g}{l \Omega^2} \tan \theta_0$$

Graphically, there is a unique solution  $\theta_0 \in [0, \frac{\pi}{2}] :$



(f) Small oscillations about  $\theta_0$  : Let  $\theta = \theta_0 + \epsilon$ , in which case

$$\ddot{\epsilon} = -W_{\text{eff}}''(\theta_0) \epsilon + \cancel{\mathcal{O}(\epsilon^2)} \quad \epsilon \text{ small}$$

$\Rightarrow \omega = \sqrt{W_{\text{eff}}''(\theta_0)}$  is small oscillation frequency

$$W_{\text{eff}}'' = + \frac{g}{l} \cos \theta + \Omega^2 \frac{a}{l} \sin \theta - \Omega^2 \cos 2\theta$$

$$\theta_0 = \frac{\pi}{4} \Rightarrow W_{\text{eff}}''(\theta_0) = \frac{1}{\sqrt{2}} \left( \frac{g}{l} + \Omega^2 \frac{a}{l} \right)$$

$$\text{But } \theta_0 = \frac{\pi}{4} \Rightarrow \frac{a}{l} + \frac{1}{\sqrt{2}} = \frac{g}{l \Omega^2}$$

$$\text{So, } \Omega^2 = \frac{g/l}{\frac{1}{\sqrt{2}} + \frac{a}{l}} = \frac{g}{l\sqrt{2}}$$

This gives

$$\omega^2 = \omega_{\text{eff}}^2(\theta_0) = \frac{1}{\sqrt{2}} \frac{g}{l} \left(1 + \frac{1}{2}\right) = \frac{3}{2\sqrt{2}} \frac{g}{l}$$

With  $\omega_0 = \sqrt{g/l}$ , then,

$$\Omega = 2^{-1/4} \omega_0$$

$$\omega = \left(\frac{3}{4}\sqrt{2}\right)^{1/2} \omega_0$$