

[1]  $m\ddot{x} = -Kx \Rightarrow T = \frac{1}{2}m\dot{x}^2, U = \frac{1}{2}Kx^2; E = T + U$   
 $x(t) = a \sin(\omega t + \varphi); \omega = \left(\frac{K}{m}\right)^{1/2}; T = \frac{2\pi}{\omega} = \text{period}$

• time averages:

$$\langle T \rangle = \frac{\omega}{2\pi} \int_0^{2\pi/\omega} dt \frac{1}{2} m a^2 \omega^2 \cos^2(\omega t + \varphi) = \frac{1}{4} m a^2 \omega^2 = \frac{1}{2} E$$

$$\langle U \rangle = \frac{\omega}{2\pi} \int_0^{2\pi/\omega} dt \frac{1}{2} K a^2 \sin^2(\omega t + \varphi) = \frac{1}{4} K a^2 = \frac{1}{2} E$$

• space averages: use  $\dot{x}^2 = \omega^2(a^2 - x^2)$

$$\bar{T} = \frac{1}{2} m \omega^2 \cdot \frac{1}{a} \int_0^a dx (a^2 - x^2) = \frac{1}{3} m \omega^2 a^2 = \frac{2}{3} E$$

$$\bar{U} = \frac{1}{2} K a^2 \cdot \frac{1}{a} \int_0^a dx x^2 = \frac{1}{6} K a^2 = \frac{1}{3} E$$

Thus,  $\langle T \rangle = \langle U \rangle = \frac{1}{2} E; \bar{T} = 2\bar{U} = \frac{2}{3} E.$

[2]  $\ddot{x} + 2\beta\dot{x} + \omega_0^2 x = f(t) = f_0 \cos \Omega t$

$$\Rightarrow x(t) = R f_0 \cos(\Omega t - \delta); R = [(\omega_0^2 - \Omega^2)^2 + 4\beta^2 \Omega^2]^{-1/2}$$

(assume homogeneous sol<sup>n</sup> fully damped to zero)  $\delta = \tan^{-1}\left(\frac{2\beta\Omega}{\omega_0^2 - \Omega^2}\right)$

Energy lost by external source per cycle:

$$\Delta E = \int dx f = \int dt \dot{x} f$$

$$= \int_0^{2\pi/\Omega} dt R \Omega f_0^2 \sin(\Omega t - \delta) \cos \Omega t = \frac{\pi}{\Omega} R \Omega f_0^2 \sin \delta$$

$$= 2\pi \beta \Omega R^2 f_0^2 \quad \text{since } \sin \delta = 2\beta \Omega \cdot R$$

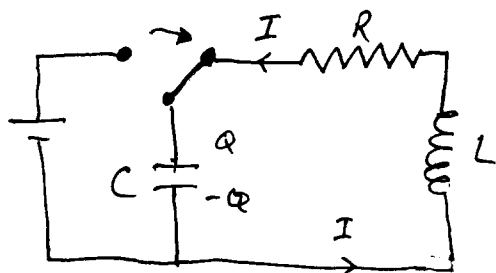
$$\langle \dot{E} \rangle = \frac{\Omega}{2\pi} \int_0^{2\pi/\Omega} dt \frac{1}{2} (\dot{x}^2 + \omega_0^2 x^2) = \frac{1}{4} (\Omega^2 + \omega_0^2) R^2 f_0^2$$

$$\Rightarrow 2\pi \frac{\langle \dot{E} \rangle}{\Delta E} = \frac{2\pi \cdot \frac{1}{4} \cdot (\Omega^2 + \omega_0^2) R^2 f_0^2}{2\pi \beta \Omega R^2 f_0^2} = \frac{\Omega^2 + \omega_0^2}{4\beta \Omega}$$

$$Q = \frac{\Omega_R}{2\beta}; \Omega_R = \sqrt{\omega_0^2 - 2\beta^2}, \text{ so for } \Omega \approx \Omega_R \quad \frac{2\pi \langle \dot{E} \rangle}{\Delta E} \approx Q$$

[3]

$V = 10 \text{ V}$



$L = 10 \text{ mH}$

$R = 100 \Omega$

$\Omega_R = 10 \text{ kHz}$

Recall  $\ddot{Q} + \frac{R}{L} \dot{Q} + \frac{1}{LC} Q = 0$  for the R-L-C circuit

$\Rightarrow \beta = \frac{R}{2L}, \quad \omega_0^2 = \frac{1}{LC}$ . Initially (at  $t=0^+$ ),

we have  $Q(0) = CV, \quad \dot{Q}(0) = 0$ .

$Q(t) = C_+ e^{-i\omega_+ t} + C_- e^{-i\omega_- t}$

$\omega_{\pm} = -i \frac{R}{2L} \pm \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$

(a)  $\Omega_R = \sqrt{\omega_0^2 - 2\beta^2} = \sqrt{\frac{1}{LC} - \frac{R^2}{2L^2}} = 10^4 \text{ s}^{-1}$

$\frac{1}{C} = \frac{R^2}{2L} + 10^8 \text{ s}^{-2} \cdot L$

MKS units  $\Rightarrow$

$C = \frac{1 \text{ F}}{10^8 \cdot 10^{-2} + \frac{10^4}{2 \cdot 10^{-2}}} = \frac{2}{3} \times 10^{-6} \text{ F} = \frac{2}{3} \mu\text{F}$

(b)  $Q(t) = C_+ e^{-i\omega_+ t} + C_- e^{-i\omega_- t}$

$\dot{Q}(t) = -i\omega_+ C_+ e^{-i\omega_+ t} - i\omega_- C_- e^{-i\omega_- t}$

$Q(0) = CV = C_+ + C_-$

$\dot{Q}(0) = 0 = -i\omega_+ C_+ - i\omega_- C_- \Rightarrow C_- = -\frac{\omega_+}{\omega_-} C_+$

$CV = C_+ \left(1 - \frac{\omega_+}{\omega_-}\right) \Rightarrow C_+ = -\frac{\omega_- CV}{\omega_+ - \omega_-}$

$C_- = \frac{\omega_+ CV}{\omega_+ - \omega_-}$

Thus,

$$Q(t) = e^{-\beta t} \left\{ \cos \nu t + \frac{\beta}{\nu} \sin \nu t \right\} \cdot CV$$

with  $\beta = \frac{R}{2L} = 5 \times 10^3 \text{ s}^{-1} = 5 \text{ kHz}$ ,  $\nu = \sqrt{\omega_0^2 - \beta^2} \Rightarrow$

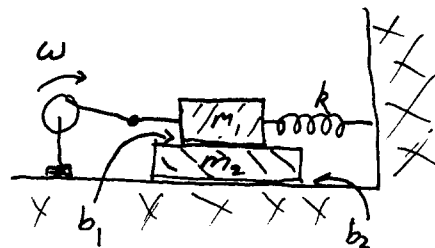
$$\nu = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}} = \sqrt{\frac{3}{2} \times 10^8 - \frac{1}{4} \times 10^8} \text{ s}^{-1} = \frac{\sqrt{5}}{2} \times 10^4 \text{ s}^{-1} = \sqrt{5} \cdot \beta$$

$$\begin{aligned} \dot{Q}(t) &= -\beta e^{-\beta t} \left\{ \cos \nu t + \frac{\beta}{\nu} \sin \nu t \right\} \cdot CV \\ &\quad + e^{-\beta t} \left\{ -\nu \sin \nu t + \beta \cos \nu t \right\} \cdot CV \\ &= -e^{-\beta t} \cdot \left( \nu + \frac{\beta^2}{\nu} \right) \sin \nu t \cdot CV \end{aligned}$$

$$CV = 10 \text{ V} \cdot \frac{2}{3} \mu\text{F} = 6 \frac{2}{3} \mu\text{C}$$

$$\begin{aligned} \dot{Q} &= -\frac{6}{\sqrt{5}} \cdot 5 \text{ kHz} \cdot e^{-5\tau} \cdot \sin(5\sqrt{5}\tau) \cdot \frac{20}{3} \mu\text{C} \\ &= -40\sqrt{5} e^{-5\tau} \sin(5\sqrt{5}\tau) \text{ mA} \quad (\tau \text{ in msec}) \end{aligned}$$

[4] Let  $x_1$  = displacement of top block relative to right wall,  $x_2$  displacement of bottom block.

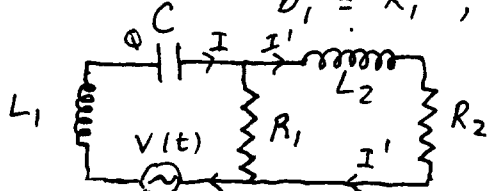


Mechanical system:

$$m_1 \ddot{x}_1 = -kx_1 - b_1(\dot{x}_1 - \dot{x}_2) + f(t)$$

$$m_2 \ddot{x}_2 = -b_2 \dot{x}_2 - b_1(\dot{x}_2 - \dot{x}_1)$$

Circuit analogy:  $m_1 \equiv L_1$ ,  $m_2 \equiv L_2$ ,  $x_1 \equiv Q$ ,  $\dot{x}_1 \equiv \dot{Q} = I$ ,  $\dot{x}_2 \equiv I'$ ,  
 $b_1 \equiv R_1$ ,  $b_2 \equiv R_2$ ,  $f(t) \equiv V(t)$ ;  $k \equiv C$



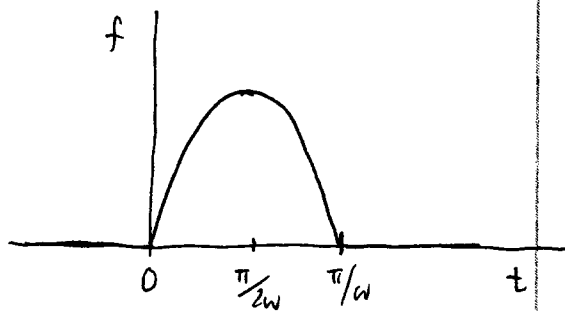
$$\begin{aligned} \frac{Q}{C} + L_1 \ddot{Q} + R_1(\dot{Q} - I') &= V(t) \\ L_2 \dot{I}' + R_2 I' + R_1(I - \dot{Q}) &= 0 \end{aligned}$$

$$[5] \ddot{x} + 2\beta\dot{x} + \omega_0^2 x = f(t) = a \sin \omega t \Theta(t) \Theta(\pi - \omega t)$$

Green's function:

$$G(s) = \nu^{-1} e^{-\beta s} \sin(\nu s) \Theta(s)$$

with  $\nu = \sqrt{\omega_0^2 - \beta^2}$ . Thus,



$$x(t) = \int_{-\infty}^{\infty} dt' G(t-t') f(t')$$

$$= \int_0^{\pi/\omega} dt' G(t-t') a \sin(\omega t')$$

$$= a \nu^{-1} \int_0^{\pi/\omega} dt' e^{-\beta(t-t')} \frac{e^{i\nu(t-t')} - e^{-i\nu(t-t')}}{2i} \frac{e^{i\omega t'} - e^{-i\omega t'}}{2i}$$

$$= \frac{a}{2\nu} \operatorname{Re} \int_0^{\pi/\omega} dt' e^{-\beta t} e^{\beta t'} \left\{ e^{-i\nu t} e^{i(\omega+\nu)t'} - e^{i\nu t} e^{i(\omega-\nu)t'} \right\}$$

$$= \frac{a}{2\nu} e^{-\beta t} \operatorname{Re} \int_0^{\pi/\omega} dt' \left\{ e^{-i\nu t} e^{(\beta+i\nu)t'} - e^{i\nu t} e^{(\beta+i\nu-i\omega)t'} \right\}$$

$$= \frac{a}{2\nu} e^{-\beta t} \operatorname{Re} \left\{ \frac{e^{-i\nu t}}{\beta+i\nu} \left( e^{(\beta+i\nu)\frac{\pi}{\omega}} e^{i\pi} - 1 \right) \right.$$

$$\left. - \frac{e^{i\nu t}}{\beta+i\nu-i\omega} \left( e^{(\beta-i\nu)\frac{\pi}{\omega}} e^{i\pi} - 1 \right) \right\}$$

$$= -\frac{a}{2\nu} e^{-\beta t} \operatorname{Re} \left\{ \frac{1 + e^{\beta\pi/\omega} e^{i\nu\pi/\omega}}{\beta+i\nu} e^{-i\nu t} \right.$$

$$\left. + \frac{1 + e^{\beta\pi/\omega} e^{-i\nu\pi/\omega}}{\beta+i\nu-i\omega} e^{i\nu t} \right\}$$

$$= -\frac{a}{2\nu} e^{-\beta t} \operatorname{Re} \left\{ \frac{e^{-i\nu t} + e^{\pi\beta/\omega} e^{i\nu(\frac{\pi}{\omega}-t)}}{\sqrt{\beta^2 + (\omega+\nu)^2}} e^{-i \tan^{-1}(\frac{\omega+\nu}{\beta})} \right.$$

$$\left. + \frac{e^{i\nu t} + e^{\pi\beta/\omega} e^{-i\nu(\frac{\pi}{\omega}-t)}}{\sqrt{\beta^2 + (\omega-\nu)^2}} e^{-i \tan^{-1}(\frac{\omega-\nu}{\beta})} \right\}$$

$$x(t) = -\frac{a}{2v} e^{-\beta t} \left\{ \frac{\cos\left(\nu t + \tan^{-1}\left(\frac{\omega + \nu}{\beta}\right)\right) + e^{\pi\beta/\omega} \cos\left(\nu\left(t - \frac{\pi}{\omega}\right) + \tan^{-1}\left(\frac{\omega + \nu}{\beta}\right)\right)}{\sqrt{\beta^2 + (\omega + \nu)^2}} \right. \\ \left. + \frac{\cos\left(\nu t + \tan^{-1}\left(\frac{\nu - \omega}{\beta}\right)\right) + e^{\pi\beta/\omega} \cos\left(\nu\left(t - \frac{\pi}{\omega}\right) + \tan^{-1}\left(\frac{\nu - \omega}{\beta}\right)\right)}{\sqrt{\beta^2 + (\omega - \nu)^2}} \right\}$$

$x(t)$

response starts at  $t = 0$