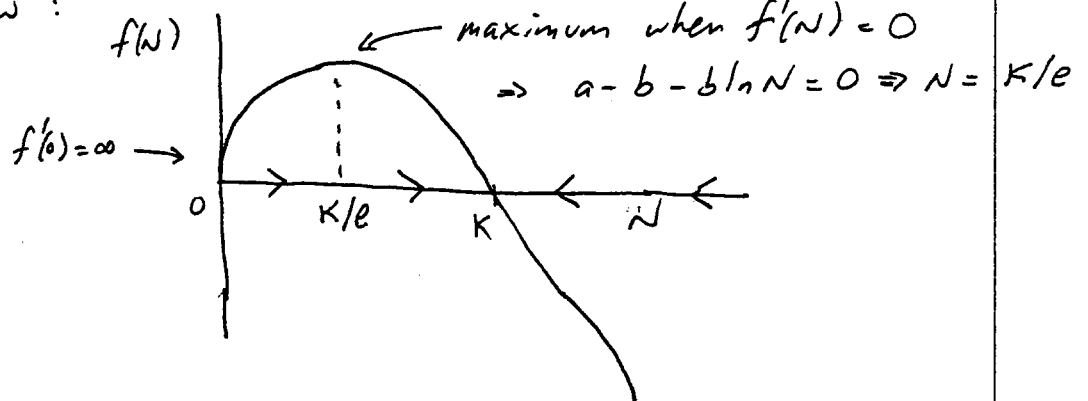


$$[1] \dot{N} = aN - bN \ln N = f(N)$$

$$f(N) = 0 \Rightarrow N=0, \ln N = \frac{a}{b} \Rightarrow N = K \equiv \exp\left(\frac{a}{b}\right)$$

Phase flow:



Analytic solution: set $y \equiv \ln N \Rightarrow$

$$\dot{y} = a - by$$

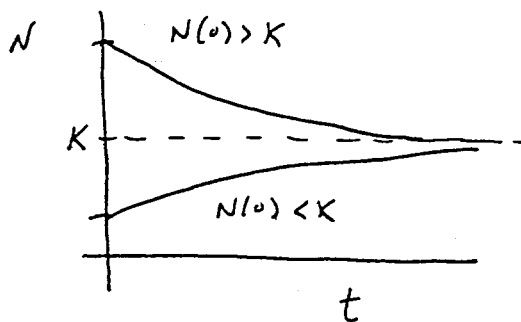
$$\frac{dy}{a-by} = -\frac{1}{b} d \ln(a-by) = dt$$

$$\ln\left(\frac{a-by(t)}{a-by(0)}\right) = -bt$$

$$y(t) = \frac{a}{b} + \left(y(0) - \frac{a}{b}\right) e^{-bt}$$

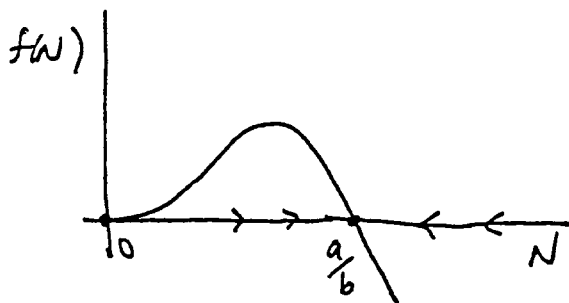
$$\ln N = \ln K + \ln\left(\frac{N(0)}{K}\right) e^{-bt}$$

$$N(t) = K \cdot \left(\frac{N(0)}{K}\right) e^{-bt}$$



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[2] $\dot{N} = aN^2 - bN^3 = N^2(a - bN)$. Fixed points at $N=0, N=\frac{a}{b}$.



$N=0$: unstable

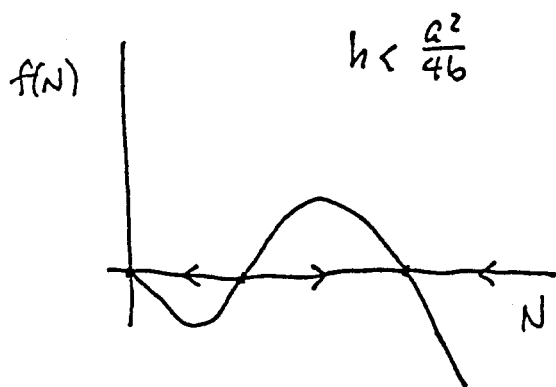
$N = \frac{a}{b}$: stable

Harvested dynamics : $\dot{N} = -hN + aN^2 - bN^3$

Now $f(N) = -N(bN^2 - aN + h)$. Set $bN^2 - aN + h = 0$:

$$N_{\pm} = \frac{a \pm \sqrt{a^2 - 4bh}}{2b}$$

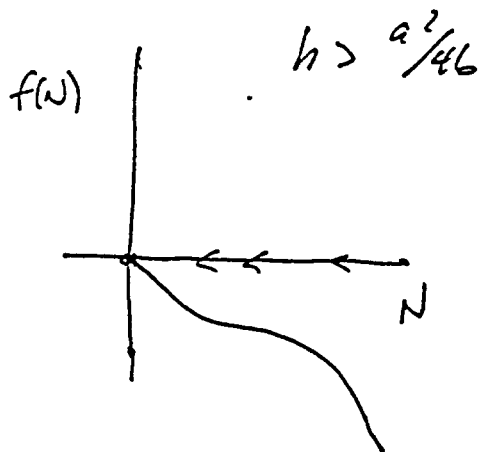
If $h > h_c = \frac{a^2}{4b}$, there are no real roots, and $f(N) < 0$, meaning $N^* = 0$ is the only fixed point. If $h < h_c$, we have three fixed points:



$N = 0$ (stable)

$N = \frac{a - \sqrt{a^2 - 4bh}}{2b}$ (unstable)

$N = \frac{a + \sqrt{a^2 - 4bh}}{2b}$ (stable)



$N = 0$ (stable)

For $h < \frac{a^2}{4b}$, we have

$$R = h N_{\text{stable}}^* = \frac{h}{2b} \cdot \left[a + \sqrt{a^2 - 4bh} \right]$$

$$\frac{\partial R}{\partial h} = \frac{1}{2b} \cdot \left\{ a + \sqrt{a^2 - 4bh} - \frac{1}{2} \frac{4bh}{\sqrt{a^2 - 4bh}} \right\}$$

$$\frac{\partial R}{\partial h} = 0 \Rightarrow a + \frac{3}{2} (a^2 - 4bh)^{1/2} - \frac{a^2}{2} (a^2 - 4bh)^{-1/2} = 0$$

$$\frac{3}{2} (a^2 - 4bh) + a (a^2 - 4bh)^{1/2} - \frac{a^2}{2} = 0$$

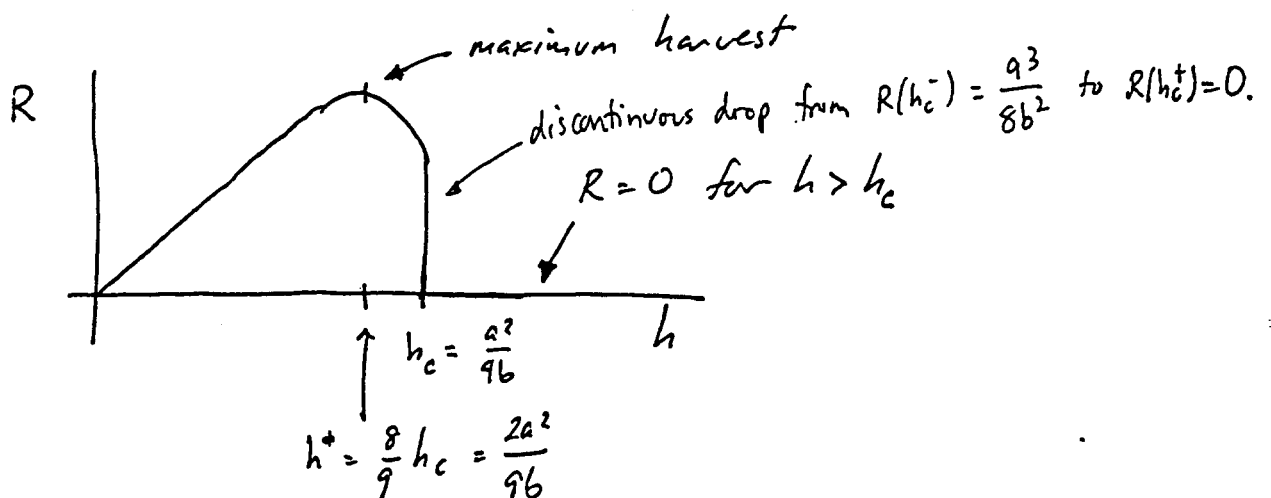
$$\Rightarrow (a^2 - 4bh)^{1/2} = \frac{-a \pm \sqrt{a^2 - 4 \cdot \frac{3}{2} \cdot \frac{a^2}{2}}}{3} = \cancel{-\frac{a}{3}}, \frac{a}{3}$$

must take positive root!

Thus, $a^2 - 4bh = \frac{a^2}{9} \Rightarrow h^* = \frac{2a^2}{9b}$. Note $h^* < h_c$.

$$\text{For } h = h^*, R = \frac{1}{2b} \cdot \frac{2a^2}{9b} \cdot \left[a + \frac{a}{3} \right] = \frac{4a^3}{27b^2}$$

$$\text{For } h = h_c, R = \frac{1}{2b} \cdot \frac{a^2}{4b} \cdot a = \frac{a^3}{8b^2}. \text{ Thus,}$$



[3] (a) $f(u) = a$ with $a \neq 0$ has no fixed points

$$\dot{u} = a \Rightarrow u(t) = u(0) + at$$

(b) $f(u) = 0$ has all $u \in \mathbb{R}$ as fixed points

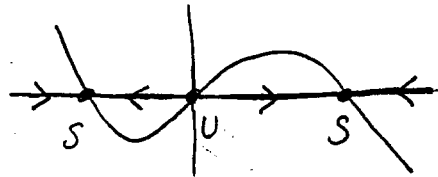
$$\dot{u} = 0 \Rightarrow u(t) = u(0)$$

(c) $f(u) = a \sin(\pi u)$ has all $u \in \mathbb{Z}$ as fixed points and no others ($a \neq 0$).

$$\dot{u} = a \sin(\pi u) \Rightarrow \frac{du}{\sin(\pi u)} = \frac{1}{\pi} d \ln \tan\left(\frac{1}{2}\pi u\right) = a dt$$

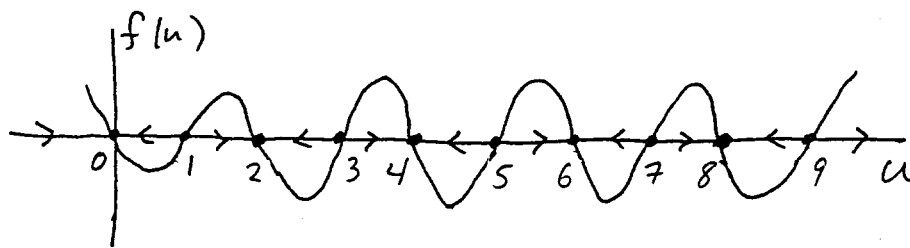
$$u(t) = \frac{2}{\pi} \tan^{-1} \left[\tan\left(\frac{\pi}{2} u(0)\right) e^{\pi a t} \right]$$

(d) It is impossible to have precisely three fixed points, all stable. Stable FPs alternate with unstable FPs. At best one could have two SFP and one UFP, e.g.



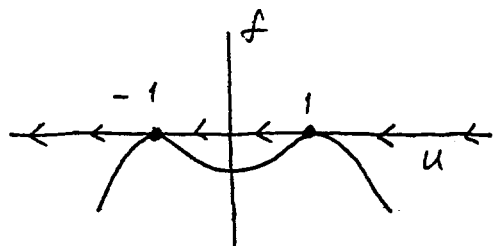
(e) $f(u) = u(u-1)(u-2)(u-3)(u-4)(u-5)(u-6)(u-7)(u-8)(u-9)$

has 10 FP at $u = 0, 1, \dots, 9$:



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(f) To have precisely two FP and $f(u) \leq u$ & u is nongeneric. Example: $f(u) = -a(u^2 - 1)^2$ with $a > 0$:

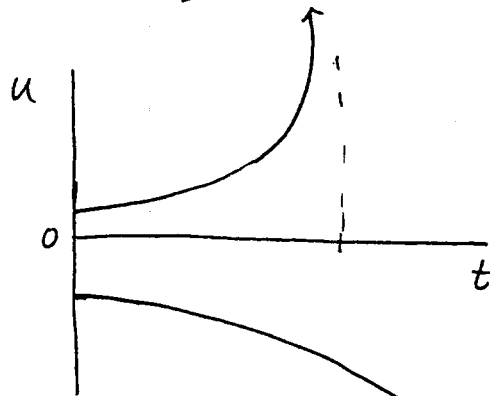
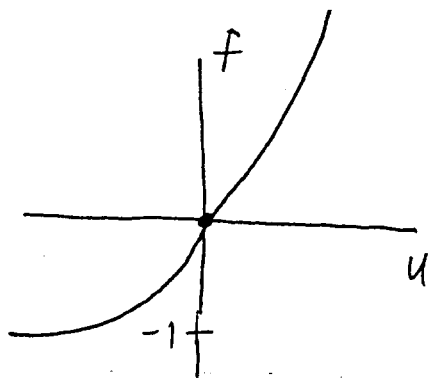


$u = \pm 1$ are both half-stable FP

(g) In order that $u > 0$ escape to $+\infty$ in finite time, $f(u)$ must grow faster than u for $u > 0$. Similarly, in order that $u < 0$ not escape to $-\infty$ in finite time, $f(u)$ cannot grow faster than u for $u < 0$. An example satisfying both criteria is $f(u) = [e^u - 1]/\tau$ (note $f(0) = 0$). Solution: $\tau > 0$

$$\frac{du}{e^u - 1} = d \ln(1 - e^{-u}) = dt/\tau$$

$$u(t) = -\ln \left[1 + (e^{-u(0)} - 1) e^{t/\tau} \right]$$



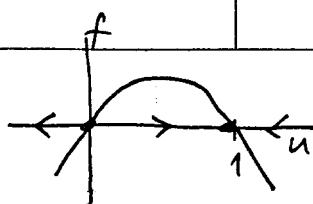
$$u(0) > 0 \Rightarrow t_\infty = \tau \ln \left(\frac{1}{1 - e^{-u(0)}} \right)$$

$$u(0) < 0 \Rightarrow u(t) \sim -\frac{t}{\tau} - \ln(e^{-u(0)} - 1) + \dots \text{ as } t \rightarrow \infty$$

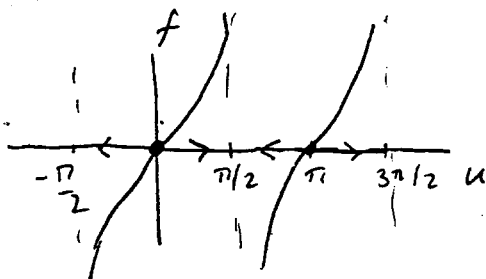
[4] (a) $\dot{u} = u(1-u)$

$u = 0$: unstable

$u = 1$: stable



(b) $\dot{u} = \tan u$

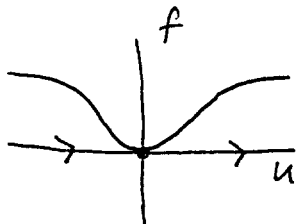


$u = \pi k$ ($k \in \mathbb{Z}$) :
unstable

$u = \pi(k + \frac{1}{2})$:
 $f(u)$ undefined

(c) $\dot{u} = 1 - e^{-u^2}$

$u = 0$: half-stable

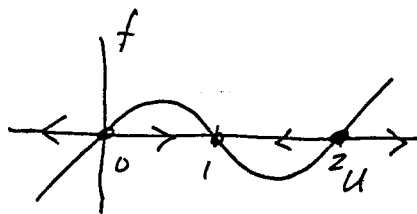


(d) $\dot{u} = u(1-u)(2-u)$

$u = 0$: unstable

$u = 1$: stable

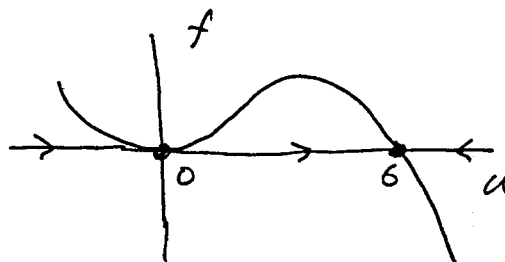
$u = 2$: unstable



(e) $\dot{u} = u^2(6-u)$

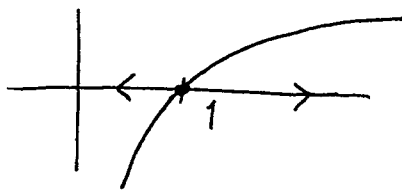
$u = 0$: half-stable

$u = 6$: stable



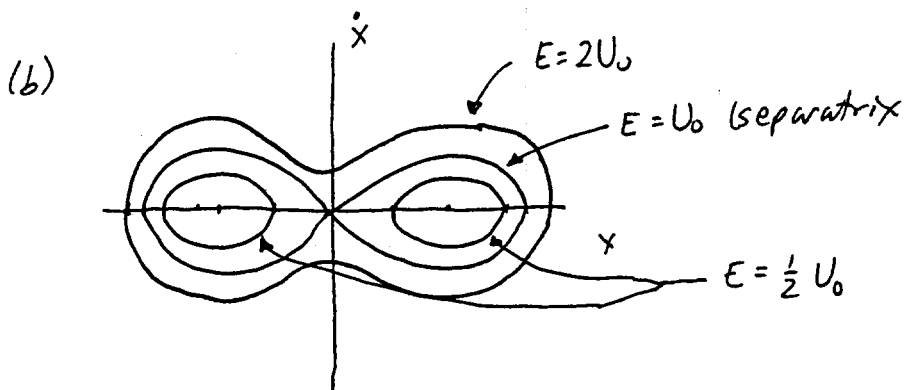
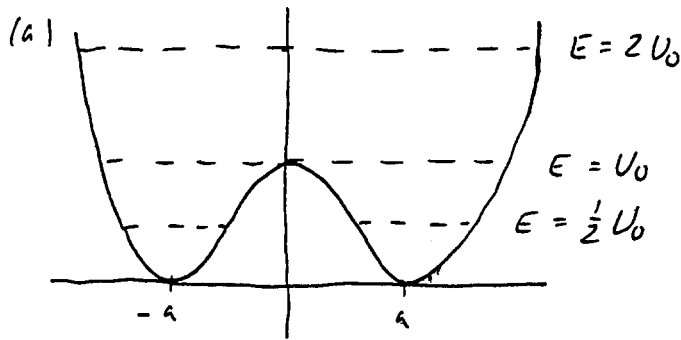
(f) $\dot{u} = \ln u$

$u = 1$: unstable



$$[5] U(x) = U_0 \left(\frac{x^2}{a^2} - 1 \right)^2$$

This function is non-negative and has minima at $x = \pm a$, where $U(\pm a) = 0$:



(c) Expand $U(x)$ in the vicinity of $x=a$:

$$x \approx a + \epsilon \quad (\epsilon \text{ small}) \Rightarrow$$

$$U(a+\epsilon) = U(a) + U'(a)\epsilon + \frac{1}{2}U''(a)\epsilon^2 + \dots$$

$$U(x) = U_0 \left\{ \frac{x^4}{a^4} - \frac{2x^2}{a^2} + 1 \right\} \Rightarrow U(a) = 0, U'(a) = 0, U''(a) = \frac{8U_0}{a^2}$$

$$m\ddot{\epsilon} = -U''(a)\epsilon - U'''(a)\epsilon^2 - \dots \quad \epsilon \text{ small}$$

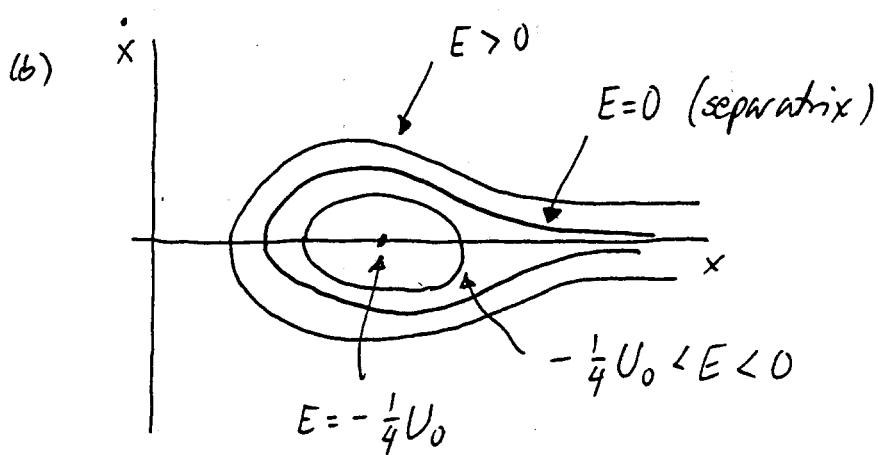
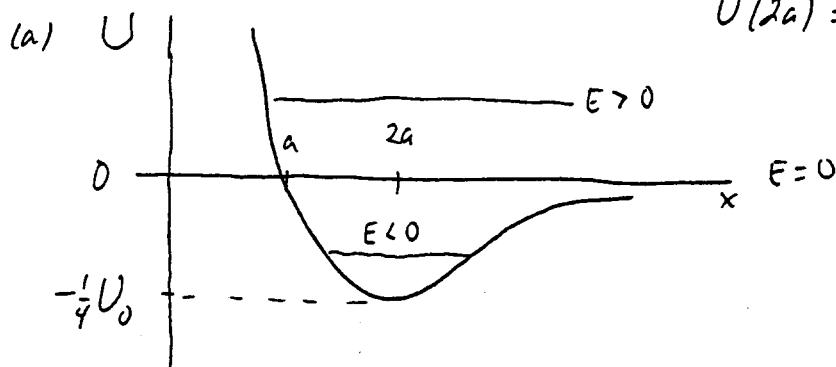
$$\Rightarrow \omega = \sqrt{\frac{U''(a)}{m}} = \sqrt{\frac{8U_0}{ma^2}}$$

$$[6] \quad U(x) = U_0 \left(\frac{a^2}{x^2} - \frac{a}{x} \right)$$

$$U(x) = 0 \Rightarrow x = a \quad ; \quad U'(x) = U_0 \left(-\frac{2a^2}{x^3} + \frac{a}{x^2} \right)$$

$$U'(x) = 0 \Rightarrow x = 2a$$

$$U(2a) = U_{\min} = -\frac{1}{4}U_0$$



(c) We have

$$T(E) = \sqrt{2m} \int_{x_L(E)}^{x_R(E)} \frac{dx}{\sqrt{E - U(x)}}$$

where $x_{L,R}(E)$ are the turning points. Let's take

$$E = -\lambda U_0 \quad \text{with} \quad 0 < \lambda < \frac{1}{4}$$

First solve for turning points:

$$U(x) = U_0 \left(\frac{a^2}{x^2} - \frac{a}{x} \right) = -\lambda U_0$$

Thus,
$$\lambda \left(\frac{x}{a}\right)^2 - \frac{x}{a} + 1 = 0$$

$$\frac{x}{a} = \frac{1 \pm \sqrt{1 - 4\lambda}}{2\lambda} \equiv s_{\pm}$$

The period is

$$\begin{aligned} T &= \sqrt{2m} \int_{as_-}^{as_+} \frac{dx}{\sqrt{-\lambda U_0 + U_0 \frac{a}{x} - U_0 \frac{a^2}{x^2}}} \\ &= \sqrt{\frac{2ma^2}{\lambda U_0}} \int_{s_-}^{s_+} \frac{s ds}{\sqrt{(s_+ - s)(s - s_-)}} \end{aligned}$$

We can do the integral! Let

$$s \equiv \frac{1}{2}(s_+ + s_-) + \frac{1}{2}(s_+ - s_-)t$$

$$ds = \frac{1}{2}(s_+ - s_-)t$$

Find

$$T(\lambda) = \sqrt{\frac{2ma^2}{\lambda U_0}} \int_{-1}^1 dt \frac{\frac{1}{2}(s_+ + s_-) + \frac{1}{2}(s_+ - s_-)t}{\sqrt{1+t^2}}$$

$$= \frac{\pi}{2} \sqrt{\frac{2ma^2}{U_0 \lambda^3}} \quad ; \quad T(\lambda = \frac{1}{8}) = \frac{\pi}{32} \sqrt{\frac{ma^2}{U_0}}$$

Note that $U''(2a) = \frac{1}{8} \frac{U_0}{a^2}$ so near $x = 2a$ we have

$\omega_0 = (U_0/8ma^2)^{1/2}$. Our expression gives for $\lambda = \frac{1}{4}$

$$T(\lambda = \frac{1}{4}) = 4\pi \sqrt{\frac{2ma^2}{U_0}} \Rightarrow \omega_0 = \frac{2\pi}{T} = \left(\frac{U_0}{8ma^2}\right)^{1/2} \quad \checkmark$$

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