

Supplementary Lecture Notes (see for example: ~~Maradudin~~)

Maradudin, Montroll & Weiss: (1)
 "Theory of Lattice Dynamics in the Harmonic approximation"
 - (Bell & Turnbull Eds.) Series on "SOLID STATE PHYSICS"

General Theory of Lattice Dynamics in 3 Dimensions (one atom / primitive cell)

Let $u_{l,\alpha}$ denote the displacement of the atom in the l^{th} unit cell in the α -direction ($\alpha = 1, 2, 3$ or x, y, z) from equilibrium position

Expand the Potential Energy Function of the Crystal (function of atom positions) in powers of displacements (Taylor series)

$$\Phi = \Phi_0 + \sum_{l,\alpha} \left(\frac{\partial \Phi}{\partial u_{l,\alpha}} \right)_0 u_{l,\alpha} + \frac{1}{2} \sum_{\substack{l,l' \\ \alpha,\beta}} \left(\frac{\partial^2 \Phi}{\partial u_{l,\alpha} \partial u_{l',\beta}} \right)_0 u_{l,\alpha} u_{l',\beta} + \dots \quad (1)$$

Φ_0 = Equilibrium Pot. Energy (all atoms in their equilibrium positions)

$()_0$ means derivatives are to be taken at the equilibrium configuration

$\left[- \left(\frac{\partial \Phi}{\partial u_{l,\alpha}} \right)_0 \right]$ is the Force on atom l in the α -direction at equilibrium

which must vanish by definition, so second term is zero

If we stop at the 3rd term, we neglect cubic & higher order

(anharmonic) powers of the displacements \rightarrow leads to "Harmonic approximation" call $\left(\frac{\partial^2 \Phi}{\partial u_{l,\alpha} \partial u_{l',\beta}} \right)_0 \equiv \Phi_{\alpha\beta}(l, l')$

Now consider a situation where we have arbitrary displacements

$u_{l,\alpha}$ of the atoms from equilibrium.

Force on atom l in α -direction is $-\left(\frac{\partial \Phi}{\partial u_{l,\alpha}} \right)$ in displaced configuration

$$= - \sum_{l',\beta} \left[\Phi_{\alpha\beta}(l, l') + \Phi_{\alpha\beta}(l', l) \right] u_{l',\beta}$$

because a particular $u_{l,\alpha}$ appears twice in the sum of Eq. (1).

By symmetry $\phi_{\alpha\beta}(l,l') = \phi_{\alpha\beta}(l',l)$

$\approx F_{l,\alpha} = - \sum_{l'\beta} \phi_{\alpha\beta}(l,l') u_{l'\beta} = M \frac{d^2 u_{l,\alpha}}{dt^2}$ (2)

Now by general running wave solution

$u_{l,\alpha} = \phi e_{\alpha} e^{i(\vec{q} \cdot \vec{l} - \omega t)}$ (3) \vec{l} = position of l^{th} unit cell atom

\vec{e}_{α} is unit vector for ~~the~~ direction of displacement (polarization vector)

Substituting in Eq. (2), we get

$-M\omega^2 \phi e_{\alpha} e^{i(\vec{q} \cdot \vec{l} - \omega t)} = - \sum_{l'\beta} \phi_{\alpha\beta}(l,l') \phi e_{\beta} e^{i(\vec{q} \cdot \vec{l}' - \omega t)}$

Now

or $\frac{1}{M} \sum_{l'\beta} \phi_{\alpha\beta}(\vec{l}, \vec{l}') e^{i\vec{q} \cdot (\vec{l}' - \vec{l})} e_{\beta} - \omega^2 e_{\alpha} = 0$ (4)

~~Define~~ Define $\frac{1}{M} \sum_{l'\beta} \phi_{\alpha\beta}(\vec{l}, \vec{l}') e^{i\vec{q} \cdot (\vec{l}' - \vec{l})} = D_{\alpha\beta}(\vec{q})$ (5)

(By translational invariance $\phi_{\alpha\beta}(\vec{l}, \vec{l}')$ is function of $(\vec{l}' - \vec{l})$ only, so can choose \vec{l} as origin unit cell $\vec{l} = 0$ in Eq. (5))

only, so can choose \vec{l} as origin unit cell $\vec{l} = 0$ in Eq. (5)

$\therefore D_{\alpha\beta}(\vec{q}) = \frac{1}{M} \sum_{\vec{l}} \phi_{\alpha\beta}(0, \vec{l}) e^{i\vec{q} \cdot \vec{l}}$ (6)

(Fourier series in 3D)

$[D_{\alpha\beta}(\vec{q})]$ is a (3×3) matrix called the Dynamical Matrix

$\phi_{\alpha\beta}(0, \vec{l})$ is called the Force Constant matrix between

atoms at $0 \rightarrow \vec{l}$. (In general it is a (3×3) matrix - or tensor)

(3)

Then Eq. (4) can be written as

$$\sum_{\beta} D_{\alpha\beta}(\vec{q}) e_{\beta} - \omega^2 e_{\alpha} = 0 \quad (3 \text{ equations, one for each } \alpha!)$$

$$\text{or } \sum_{\beta} [D_{\alpha\beta}(\vec{q}) - \delta_{\alpha\beta} \omega^2] e_{\beta} = 0. \quad (7)$$

where the Kronecker delta $\delta_{\alpha\beta} = 1$ if $\alpha = \beta$; $= 0$ if $\alpha \neq \beta$

Eq. (7) represents a set of 3 linear homogeneous equations:

$$(D_{11}(\vec{q}) - \omega^2) e_1 + D_{12}(\vec{q}) e_2 + D_{13}(\vec{q}) e_3 = 0$$

$$D_{21}(\vec{q}) e_1 + (D_{22}(\vec{q}) - \omega^2) e_2 + D_{23}(\vec{q}) e_3 = 0$$

$$D_{31}(\vec{q}) e_1 + D_{32}(\vec{q}) e_2 + (D_{33}(\vec{q}) - \omega^2) e_3 = 0$$

which implies that e_1, e_2, e_3 have a non-trivial solution if + only

$$\text{if } \begin{vmatrix} D_{11} - \omega^2 & D_{12} & D_{13} \\ D_{21} & D_{22} - \omega^2 & D_{23} \\ D_{31} & D_{32} & D_{33} - \omega^2 \end{vmatrix} = 0 \quad (8)$$

→ 3 solutions for ω^2 as a function of \vec{q} → 3 branches of phonon dispersion curves.

Eq. (7) may also be written as the matrix equation

$$\underline{D} \underline{e} = \omega^2 \underline{e} \quad (9)$$

\underline{D} is the (3×3) matrix $D_{\alpha\beta}(\vec{q})$, \underline{e} is the vector $\begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix}$

Eq. (9) is an example of the Eigenvalue problem in physics.

(4)

$(\omega^2)_j$ is one of the 3 eigenvalues of the (3×3) Matrix \underline{D} obtained by solving the determinantal eigenvalue equation (8)

\underline{e}_j is the corresponding eigenvector ($j = 1, 2, 3$)

There are 3 eigenvectors - one for each eigenvalue.

By the properties of linear equations & matrices, these eigenvectors are mutually orthogonal, i.e. $\underline{e}_j \cdot \underline{e}_{j'} = \delta_{jj'}$

$$\sum_a e_{ja} e_{j'a} = \delta_{jj'} \quad (\text{e.g. longitudinal \&}$$

transverse polarization vectors but in general direction of \vec{q} polarization vectors will not necessarily be parallel or \perp to \vec{q} (but they will be mutually orthogonal)